

Thermochemical Non-Equilibrium Reentry Flows in Two-Dimensions – Part I

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Abstract: - This work presents a numerical tool implemented to simulate inviscid and viscous flows employing the reactive gas formulation of thermal and chemical non-equilibrium. The Euler and Navier-Stokes equations, employing a finite volume formulation, on the context of structured and unstructured spatial discretizations, are solved. These variants allow an effective comparison between the two types of spatial discretization aiming verify their potentialities: solution quality, convergence speed, computational cost, etc. The aerospace problem involving the hypersonic flow around a blunt body, in two-dimensions, is simulated. The reactive simulations will involve an air chemical model of five species: N, O, N₂, O₂ and NO. Seventeen chemical reactions, involving dissociation and recombination, will be simulated by the proposed model. The Arrhenius formula will be employed to determine the reaction rates and the law of mass action will be used to determine the source terms of each gas species equation.

Key-Words: - Thermochemical non-equilibrium, Reentry flow, Five species chemical model, Arrhenius formula, Structured and unstructured solutions, Euler and Navier-Stokes equations, Two-Dimensions.

1 Introduction

The study of hypersonic flows has gained momentum with the advent of concepts like the National AeroSpace Plane (NASP) and similar transatmospheric vehicles. Under the very high velocity and temperature conditions experienced by hypersonic vehicles, departure from chemical and thermal equilibrium occurs. Properties of air change dramatically as new chemical species are produced at the expense of others. The simple one temperature model used to describe the energy of air becomes inapplicable, and it becomes necessary to consider one or more additional temperatures (corresponding to vibrational and electronic energies). Determination of aerothermal loads on blunt bodies in such an environment is of great importance.

In high speed flows, any adjustment of chemical composition or thermodynamic equilibrium to a change in local environment requires certain time. This is because the redistribution of chemical species and internal energies require certain number of molecular collisions, and hence a certain characteristic time. Chemical non-equilibrium occurs when the characteristic time for the chemical reactions to reach local equilibrium is of the same order as the characteristic time of the fluid flow. Similarly, thermal non-equilibrium occurs when the characteristic time for translation and various

internal energy modes to reach local equilibrium is of the same order as the characteristic time of the fluid flow. Since chemical and thermal changes are the results of collisions between the constituent particles, non-equilibrium effects prevail in high-speed flows in low-density air.

In chemical non-equilibrium flows the mass conservation equation is applied to each of the constituent species in the gas mixture. Therefore, the overall mass conservation equation is replaced by as many species conservation equations as the number of chemical species considered. The assumption of thermal non-equilibrium introduces additional energy conservation equations – one for every additional energy mode. Thus, the number of governing equations for non-equilibrium flow is much bigger compared to those for perfect gas flow. A complete set of governing equations for non-equilibrium flow may be found in [1-2].

Analysis of non-equilibrium flow is rather complex because (1) the number of equations to be solved is much larger than the Navier-Stokes equations, and (2) there are additional terms like the species production, mass diffusion, and vibrational energy relaxation, etc., that appear in the governing equations. In a typical flight of the NASP flying at Mach 15, ionization is not expected to occur, and a 5-species air is adequate for the analysis (see [3]). Since the rotational characteristic temperatures for

the constituent species (namely N, O, N₂, O₂ and NO) are small, the translational and rotational energy modes are assumed to be in equilibrium, whereas the vibrational energy mode is assumed to be in non-equilibrium. [4] has simplified the thermodynamic model by assuming a harmonic oscillator to describe the vibrational energy. Ionic species and electrons are not considered. This simplifies the set of governing equations by eliminating the equation governing electron and electronic excitation energy. [4] has taken the complete set of governing equations from [1], and simplified them for a five-species two-temperature air model.

The problems of chemical non-equilibrium in the shock layers over vehicles flying at high speeds and high altitudes in the Earth's atmosphere have been discussed by several investigators ([5-8]). Most of the existing computer codes for calculating the non-equilibrium reacting flow use the one-temperature model, which assumes that all of the internal energy modes of the gaseous species are in equilibrium with the translational mode ([7-8]). It has been pointed out that such a one-temperature description of the flow leads to a substantial overestimation of the rate of equilibrium because of the elevated vibrational temperature [6]. A three-temperature chemical-kinetic model has been proposed by [9] to describe the relaxation phenomena correctly in such a flight regime. However, the model is quite complex and requires many chemical rate parameters which are not yet known. As a compromise between the three-temperature and the conventional one-temperature model, a two-temperature chemical-kinetic model has been developed ([10-11]), which is designated herein as the TT_v model. The TT_v model uses one temperature T to characterize both the translational energy of the atoms and molecules and the rotational energy of the molecules, and another temperature T_v to characterize the vibrational energy of the molecules, translational energy of the electrons, and electronic excitation energy of atoms and molecules. The model has been applied to compute the thermodynamic properties behind a normal shock wave in a flow through a constant-area duct ([10-11]). Radiation emission from the non-equilibrium flow has been calculated using the Non-equilibrium Air Radiation (NEQAIR) program ([12-13]). The flow and the radiation computations have been packaged into a single computer program, the Shock-Tube Radiation Program (STRAP) ([11]).

A first-step assessment of the TT_v model was made in [11] where it was used in computing the flow properties and radiation emission from the

flow in a shock tube for pure nitrogen undergoing dissociation and weak ionization (ionization fraction less than 0.1%). Generally good agreement was found between the calculated radiation emission and those obtained experimentally in shock tubes ([14-16]). The only exception involved the vibrational temperature. The theoretical treatment of the vibrational temperature could not be validated because the existing data on the vibrational temperature behind a normal shock wave ([16]) are those for an electronically excited state of the molecular nitrogen ion N₂⁺ instead of the ground electronic state of the neutral nitrogen molecule N₂ which is calculated in the theoretical model. The measured vibrational temperature of N₂⁺ was much smaller than the calculated vibrational temperature for N₂.

This work, first of this study, describes a numerical tool to perform thermochemical non-equilibrium simulations of reactive flow in two-dimensions. The [17] scheme, in its first- and second-order versions, is implemented to accomplish the numerical simulations. The Euler and Navier-Stokes equations, on a finite volume context and employing structured and unstructured spatial discretizations, are applied to solve the "hot gas" hypersonic flow around a blunt body in two-dimensions. The second-order version of the [17] scheme is obtained from a "MUSCL" extrapolation procedure in a context of structured spatial discretization. In the unstructured context, only first-order solutions are obtained. The convergence process is accelerated to the steady state condition through a spatially variable time step procedure, which has proved effective gains in terms of computational acceleration (see [18-19]).

The reactive simulations involve an air chemical model of five species: N, O, N₂, O₂ and NO. Seventeen chemical reactions, involving dissociation and recombination, are simulated by the proposed model. The Arrhenius formula is employed to determine the reaction rates and the law of mass action is used to determine the source terms of each gas species equation.

The results have demonstrated that the most correct aerodynamic coefficient of lift is obtained by the [17] scheme with second-order accuracy, in an inviscid formulation, to a reactive condition of thermochemical non-equilibrium. Considering thermochemical non-equilibrium, the cheapest algorithm was due to [17], inviscid, first-order accurate, unstructured. Moreover, the shock position is closer to the geometry as using the reactive formulation than the ideal gas formulation. It was

verified in the inviscid and viscous cases.

2 Formulation to Reactive Flow in Thermochemical Non-Equilibrium

2.1 Reactive Equations in Two-Dimensions

The reactive Navier-Stokes equations in thermal and chemical non-equilibrium were implemented on a finite volume context, in the two-dimensional space. In this case, these equations in integral and conservative forms can be expressed by:

$$\frac{\partial}{\partial t} \int_V Q dV + \int_S \vec{F} \cdot \vec{n} dS = \int_V S_{CV} dV, \text{ with}$$

$$\vec{F} = (E_e - E_v) \vec{i} + (F_e - F_v) \vec{j}, \quad (1)$$

where: Q is the vector of conserved variables, V is the volume of a computational cell, \vec{F} is the complete flux vector, \vec{n} is the unity vector normal to the flux face, S is the flux area, S_{CV} is the chemical and vibrational source term, E_e and F_e are the convective flux vectors or the Euler flux vectors in the x and y directions, respectively, E_v and F_v are the viscous flux vectors in the x and y directions, respectively. The \vec{i} and \vec{j} unity vectors define the Cartesian coordinate system. Nine (9) conservation equations are solved: one of general mass conservation, two of linear momentum conservation, one of total energy, four of species mass conservation and one of the vibrational internal energy of the molecules. Therefore, one of the species is absent of the iterative process. The CFD (“Computational Fluid Dynamics”) literature recommends that the species of biggest mass fraction of the gaseous mixture should be omitted, aiming to result in a minor numerical accumulation error, corresponding to the biggest mixture constituent (in the case, the air). To the present study, in which is chosen a chemical model to the air composed of five (5) chemical species (N , O , N_2 , O_2 and NO) and seventeen (17) chemical reactions, being fifteen (15) dissociation reactions (endothermic reactions) and two (2) of exchange or recombination, this species can be the N_2 or the O_2 . To this work, it was chosen the N_2 . The vectors Q , E_e , F_e , E_v , F_v and S_{CV} can, hence, be defined as follows ([4]):

$$Q = \begin{Bmatrix} \rho \\ \rho u \\ \rho v \\ e \\ \rho_1 \\ \rho_2 \\ \rho_4 \\ \rho_5 \\ \rho e_v \end{Bmatrix}, E_e = \begin{Bmatrix} \rho u \\ \rho u^2 + p \\ \rho uv \\ \rho Hu \\ \rho_1 u \\ \rho_2 u \\ \rho_4 u \\ \rho_5 u \\ \rho e_v u \end{Bmatrix}, F_e = \begin{Bmatrix} \rho v \\ \rho uv \\ \rho v^2 + p \\ \rho Hv \\ \rho_1 v \\ \rho_2 v \\ \rho_4 v \\ \rho_5 v \\ \rho e_v v \end{Bmatrix}; \quad (2)$$

$$E_v = \frac{1}{Re} \begin{Bmatrix} 0 \\ \tau_{xx} \\ \tau_{xy} \\ \tau_{xx}u + \tau_{xy}v - q_{f,x} - q_{v,x} - \phi_x \\ -\rho_1 v_{1x} \\ -\rho_2 v_{2x} \\ -\rho_4 v_{4x} \\ -\rho_5 v_{5x} \\ -q_{v,x} - \phi_{v,x} \end{Bmatrix}; \quad (3)$$

$$F_v = \frac{1}{Re} \begin{Bmatrix} 0 \\ \tau_{xy} \\ \tau_{yy} \\ \tau_{xy}u + \tau_{yy}v - q_{f,y} - q_{v,y} - \phi_y \\ -\rho_1 v_{1y} \\ -\rho_2 v_{2y} \\ -\rho_4 v_{4y} \\ -\rho_5 v_{5y} \\ -q_{v,y} - \phi_{v,y} \end{Bmatrix}, \quad (4)$$

$$S_{CV} = \begin{Bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ \dot{\omega}_1 \\ \dot{\omega}_2 \\ \dot{\omega}_4 \\ \dot{\omega}_5 \\ \sum_{s=mol} \rho_s (e_{v,s}^* - e_{v,s}) / \tau_s + \sum_{s=mol} \dot{\omega}_s e_{v,s} \end{Bmatrix}, \quad (5)$$

in which: ρ is the mixture density; u and v are Cartesian components of the velocity vector in the x and y directions, respectively; p is the fluid static pressure; e is the fluid total energy; ρ_1, ρ_2, ρ_4 and ρ_5 are densities of the N, O, O₂ and NO, respectively; H is the mixture total enthalpy; e_v is the sum of the vibrational energy of the molecules; the τ 's are the components of the viscous stress tensor; $q_{f,x}$ and $q_{f,y}$ are the frozen components of the Fourier-heat-flux vector in the x and y directions, respectively; $q_{v,x}$ and $q_{v,y}$ are the components of the Fourier-heat-flux vector calculated with the vibrational thermal conductivity and vibrational temperature; $\rho_s v_{sx}$ and $\rho_s v_{sy}$ represent the species diffusion flux, defined by the Fick law; ϕ_x and ϕ_y are the terms of mixture diffusion; $\phi_{v,x}$ and $\phi_{v,y}$ are the terms of molecular diffusion calculated at the vibrational temperature; $\dot{\omega}_s$ is the chemical source term of each species equation, defined by the law of mass action; e_v^* is the molecular-vibrational-internal energy calculated with the translational/rotational temperature; and τ_s is the translational-vibrational characteristic relaxation time of each molecule.

The viscous stresses, in N/m², are determined, according to a Newtonian fluid model, by:

$$\tau_{xx} = 2\mu \frac{\partial u}{\partial x} - \frac{2}{3}\mu \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right),$$

$$\tau_{xy} = \mu \left(\frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \right) \text{ and } \tau_{yy} = 2\mu \frac{\partial v}{\partial y} - \frac{2}{3}\mu \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right),$$

(6)

in which μ is the fluid molecular viscosity.

The frozen components of the Fourier-heat-flux vector, which considers only thermal conduction, are defined by:

$$q_{f,x} = -k_f \frac{\partial T}{\partial x} \text{ and } q_{f,y} = -k_f \frac{\partial T}{\partial y}, \quad (7)$$

where k_f is the mixture frozen thermal conductivity, calculated conform presented in subsection 2.3.4. The vibrational components of the Fourier-heat-flux vector are calculated as follows:

$$q_{v,x} = -k_v \frac{\partial T_v}{\partial x} \text{ and } q_{v,y} = -k_v \frac{\partial T_v}{\partial y}, \quad (8)$$

in which k_v is the vibrational thermal conductivity and T_v is the vibrational temperature, what characterizes this model as of two temperatures: translational/rotational and vibrational. The calculation of T_v and k_v are demonstrated in subsections 2.2.2 and 2.3.4, respectively.

The terms of species diffusion, defined by the Fick law, to a condition of thermal non-equilibrium, are determined by ([4]):

$$\rho_s v_{sx} = -\rho D_s \frac{\partial Y_{MF,s}}{\partial x} \text{ and } \rho_s v_{sy} = -\rho D_s \frac{\partial Y_{MF,s}}{\partial y},$$

(9)

with “s” referent to a given species, $Y_{MF,s}$ being the molar fraction of the species, defined as:

$$Y_{MF,s} = \frac{\rho_s / M_s}{\sum_{k=1}^{ns} \rho_k / M_k} \quad (10)$$

and D_s is the species-effective-diffusion coefficient.

The diffusion terms ϕ_x and ϕ_y which appear in the energy equation are defined by ([20]):

$$\phi_x = \sum_{s=1}^{ns} \rho_s v_{sx} h_s \text{ and } \phi_y = \sum_{s=1}^{ns} \rho_s v_{sy} h_s, \quad (11)$$

being h_s the specific enthalpy (sensible) of the chemical species “s”. Details of the calculation of the specific enthalpy, see [21-22]. The molecular diffusion terms calculated at the vibrational temperature, $\phi_{v,x}$ and $\phi_{v,y}$, which appear in the vibrational-internal-energy equation are defined by ([4]):

$$\phi_{v,x} = \sum_{s=mol} \rho_s v_{sx} h_{v,s} \text{ and } \phi_{v,y} = \sum_{s=mol} \rho_s v_{sy} h_{v,s}, \quad (12)$$

with $h_{v,s}$ being the specific enthalpy (sensible) of the chemical species “s” calculated at the vibrational temperature T_v . The sum of Eq. (12), as also those present in Eq. (5), considers only the molecules of the system, namely: N₂, O₂ and NO.

2.2 Thermodynamic Model/Thermodynamic Properties

2.2.1 Definition of general parameters

$$p = RT \sum_{s=1}^{ns} \rho_s / M_s = \rho \sigma RT \therefore \rho \sigma = \sum_{s=1}^{ns} \rho_s / M_s = \rho \sum_{s=1}^{ns} c_s / M_s \Rightarrow$$

$$\sigma = \sum_{s=1}^{ns} c_s / M_s, \quad (13)$$

in which: σ is the mixture number in kg-mol/kg and c_s is the mass fraction (non-dimensional), defined by $c_s = \rho_s / \rho$.

$$\sigma = \sum_{s=1}^{ns} \sigma_s \Rightarrow \sigma_s = c_s / M_s ;$$

$$M_{\text{mixt}} = 1 / \sigma \therefore M_{\text{mixt}} = 1 / \sum_{s=1}^{ns} c_s / M_s ;$$

$$e_{v,s}^* = e_{v,s}(T_v = T), \quad (14)$$

with: σ_s being the number of kg-mol/kg of species "s" and M_{mixt} is the mixture molecular mass, in kg/kg-mol.

2.2.2 Thermodynamic model

(a) Mixture translational internal energy:

$$e_T = \sum_{s=1}^{ns} e_{T,s} \sigma_s = \sum_{s=1}^{ns} \left[\int_0^T C_{v,T,s}(T') dT' + h^0 \right] \sigma_s, \quad (15)$$

where: $e_{T,s}$ is the translational internal energy per kg-mol of species "s", in J/kg-mol. The specific heat at constant volume per kg-mol of species "s" due to translation, in J/(kg-mol.K), is defined by:

$$C_{v,T,s}(T) = 1.5R. \quad (16)$$

Hence,

$$e_{T,s}(T) = 1.5RT + h^0 \Rightarrow e_T(T) = \sum_{s=1}^{ns} \sigma_s (1.5RT + h^0), \quad (17)$$

with: e_T being the translational internal energy per unity of the gaseous mixture mass, in J/kg, and h^0 being the formation enthalpy of the species "s" per kg-mol of species, J/kg-mol. It is important to note that:

$$e_T(T) = \sum_{s=1}^{ns} \sigma_s (1.5RT + h^0) = \sum_{s=1}^{ns} c_s \left(1.5 \frac{R}{M_s} T + \frac{h^0}{M_s} \right) =$$

$$\sum_{s=1}^{ns} c_s (1.5R_s T + h_s^0) \Rightarrow e_T(T) = \sum_{s=1}^{ns} c_s (1.5R_s T + h_s^0), \quad (18)$$

with: R_s being the gas constant of species "s" and h_s^0 being the formation enthalpy of species "s" in J/kg. The species formation enthalpy per g-mol of species is specified in Tab. 1.

Table 1 Species formation enthalpy.

Species	N	O	N ₂	O ₂	NO
h^0 (J/g-mol) ¹	470,816.0	246,783.0	0.0	0.0	90,671.0

⁽¹⁾ As can be noted, dividing each above term by the species molecular mass and multiplying by 10^3 , it is possible to obtain the formation enthalpy in J/kg.

(b) Mixture rotational internal energy:

$$e_R = \sum_{s=1}^{ns} e_{R,s} \sigma_s = \sum_{s=1}^{ns} \left[\int_0^T C_{v,R,s}(T') dT' \right] \sigma_s =$$

$$\sum_{s=1}^{ns} \sigma_s \int_0^T C_{v,R,s}(T') dT', \quad (19)$$

where: $e_{R,s}$ is the rotational internal energy per kg-mol of species "s", in J/kg-mol. The specific heat at constant volume per kg-mol of species "s" due to rotation, in J/(kg-mol.K), is defined by:

$$C_{v,R,s} = R \Rightarrow e_{R,s}(T) = RT \therefore e_R(T) = \sum_{s=1}^{ns} \sigma_s RT$$

$$\text{or } e_R(T) = \sum_{s=1}^{ns} c_s R_s T, \quad (20)$$

with e_R being the rotational internal energy per unity of gaseous mixture mass, in J/kg.

(c) Mixture vibrational internal energy:

$$e_v = \sum_{s=\text{mol}} e_{v,s} \sigma_s = \sum_{s=\text{mol}} \sigma_s \int_0^{T_v} C_{v,v,s}(T') dT'; \text{ with}$$

$$C_{v,v,s} = C_{v,v,s}(T_v) = R \frac{e^{\theta_{v,s}/T_v}}{(e^{\theta_{v,s}/T_v} - 1)^2} \left(\frac{\theta_{v,s}}{T_v} \right)^2, \quad (21)$$

in which: e_v is the vibrational internal energy per unity of gaseous mixture mass, in J/kg; $e_{v,s}$ is the vibrational internal energy per kg-mol of species “s”, in J/kg-mol; $C_{v,v,s}$ is the specific heat at constant volume per kg-mol of species “s” due to vibration, in J/(kg-mol.K); $\theta_{v,s}$ is the characteristic vibrational temperature of species “s”, in K; and T_v is the vibrational temperature, in K. The characteristic vibrational temperature to each molecule is specified in Tab. 2, obtained from [4]. It is important to note that e_v is also directly obtained from the vector of conserved variables.

Table 2 Characteristic vibrational temperature of the molecular species.

Species	N ₂	O ₂	NO
$\theta_{v,s}$ (K)	3,390.0	2,270.0	2,740.0

It is important to note that the modes of translational and rotational internal energy are assumed completely excited and, hence, the specific heats at constant volume to these modes are temperature independent. The vibrational-internal-energy mode is admitted not be completely excited, and, hence, the vibrational specific heat at constant volume is function of the vibrational temperature. The expression above to $C_{v,v,s}$ is due to [23] and is the result of the hypothesis that the molecules can be considered as harmonic oscillators. Note that when the mode of vibrational internal energy is completely excited, i.e., when $T_v \gg \theta_{v,s}$, $C_{v,v,s} = R$.

(c) Mixture internal energy:

$$e_{\text{int}} = e_T + e_R + e_v, \quad (22)$$

which is the internal energy per unity of mixture mass, in J/kg.

(d) Frozen speed of sound:

$$C_{v,TR} = \sum_{s=1}^{ns} \sigma_s C_{v,TR,s} = \sum_{s=1}^{ns} \sigma_s \begin{pmatrix} 2.5R & \text{molecules} \\ 1.5R & \text{atoms} \end{pmatrix};$$

$$\beta = R\sigma/C_{v,TR} \therefore a_f = \sqrt{(\beta+1)p/\rho}. \quad (23)$$

The frozen speed of sound, in a thermochemical non-equilibrium model, should be employed in the calculation of the convective flux of the [17] scheme. $C_{v,TR,s}$ is the specific heat at constant volume due to translation and rotation; in other words, $C_{v,TR,s}$ is the sum of $C_{v,T,s}$ with $C_{v,R,s}$.

(e) Determination of the translational/rotational temperature:

$$\frac{e}{\rho} = \sum_{s=1}^{ns} c_s C_{v,TR,s} T + \sum_{s=1}^{ns} c_s h_s^0 + e_v + \frac{1}{2}(u^2 + v^2), \quad (24)$$

to the two-dimensional case. Hence, noting that T is constant at the right hand side of Eq. (24), it is possible to write:

$$T = \frac{1}{\sum_{s=1}^{ns} c_s C_{v,TR,s}} \left[\frac{e}{\rho} - \sum_{s=1}^{ns} c_s h_s^0 - e_v - \frac{1}{2}(u^2 + v^2) \right], \quad (25)$$

to the two-dimensional case;

(f) Determination of the vibrational temperature:

The vibrational temperature is calculated through an interactive process employing the Newton-Raphson method (details in [24]).

(g) Species pressure:

Applying the equation of a thermally perfect gas to each species:

$$p_s = \rho_s R_s T, \quad (26)$$

where: $\rho_s = c_s \rho$ is the density of species “s”, R_s is the gas constant to species “s” and T is the translational/rotational temperature.

2.3 Transport Model/Transport Physical Properties

2.3.1 Collision integrals to species i and j

In Table 3 are presented values of $\text{Log}_{10}[\pi\Omega_{i,j}^{(1,1)}]$ and $\text{Log}_{10}[\pi\Omega_{i,j}^{(2,2)}]$ to temperature values of 2,000 K and 4,000 K. The indexes i and j indicate, in the present case, the collision partners; in other words, the pair formed by one atom and one atom, one atom and one molecule, etc. These data were obtained from [1].

Table 3 Collision integrals to five chemical species: N, O, N₂, O₂ and NO.

Pairs		$\text{Log}_{10}[\pi\Omega_{i,j}^{(1,1)}]$		$\text{Log}_{10}[\pi\Omega_{i,j}^{(2,2)}]$	
i	j	2,000 K	4,000 K	2,000 K	4,000 K
N	N	-14.08	-14.11	-14.74	-14.82
	O	-14.76	-14.86	-14.69	-14.80
	N ₂	-14.67	-14.75	-14.59	-14.66
O ₂	-14.66	-14.74	-14.59	-14.66	
NO	-14.66	-14.75	-14.67	-14.66	
O	N	-14.76	-14.86	-14.69	-14.80
	O	-14.11	-14.14	-14.71	-14.79
	N ₂	-14.63	-14.72	-14.55	-14.64
O ₂	-14.69	-14.76	-14.62	-14.69	
NO	-14.66	-14.74	-14.59	-14.66	
N ₂	N	-14.67	-14.75	-14.59	-14.66
	O	-14.63	-14.72	-14.55	-14.64
	N ₂	-14.56	-14.65	-14.50	-14.58
O ₂	-14.58	-14.63	-14.51	-14.54	
NO	-14.57	-14.64	-14.51	-14.56	

The data aforementioned define a linear interpolation to values of $\text{Log}_{10}[\pi\Omega_{i,j}^{(k,k)}]$ as function of $\text{Ln}(T)$, with $k = 1, 2$, through the linear equation:

Table 3 Collision integrals to five chemical species: N, O, N₂, O₂ and NO. (Continuation)

Pairs		$\text{Log}_{10}[\pi\Omega_{i,j}^{(1,1)}]$		$\text{Log}_{10}[\pi\Omega_{i,j}^{(2,2)}]$	
i	j	2,000 K	4,000 K	2,000 K	4,000 K
O ₂	N	-14.66	-14.74	-14.59	-14.66
	O	-14.69	-14.76	-14.62	-14.69
	N ₂	-14.58	-14.63	-14.51	-14.54
O ₂	-14.60	-14.64	-14.54	-14.57	
NO	-14.59	-14.63	-14.52	-14.56	
NO	N	-14.66	-14.75	-14.67	-14.66
	O	-14.66	-14.74	-14.59	-14.66
	N ₂	-14.57	-14.64	-14.51	-14.56
O ₂	-14.59	-14.63	-14.52	-14.56	
NO	-14.58	-14.64	-14.52	-14.56	

$$\text{Log}_{10}[\pi\Omega_{i,j}^{(k,k)}](T) = \text{Log}_{10}[\pi\Omega_{i,j}^{(k,k)}](T = 2,000\text{K}) + \text{slope} \times \text{Ln}(T/2,000), \quad (27)$$

in which:

$$\text{slope} = \left\{ \text{Log}_{10}[\pi\Omega_{i,j}^{(k,k)}](T = 4,000\text{K}) - \text{Log}_{10}[\pi\Omega_{i,j}^{(k,k)}](T = 2,000\text{K}) \right\} / \text{Ln}2. \quad (28)$$

The value of $\pi\Omega_{i,j}^{(k,k)}$ is obtained from:

$$\pi\Omega_{i,j}^{(k,k)}(T) = e^{\left\{ \text{Log}_{10}[\pi\Omega_{i,j}^{(k,k)}](T = 2,000\text{K}) + \text{slope} \times \text{Ln}(T/2,000) \right\} \times \text{Ln}10}, \quad (29)$$

with the value of $\Omega_{i,j}^{(k,k)}$ in m^2 .

2.3.2 Modified collision integrals to the species i and j

[1] and [4] define the modified collision integrals to the species i and j as:

$$\Delta_{i,j}^{(1)}(T) = \frac{8}{3} \sqrt{\frac{2m_{i,j}}{\pi RT}} \pi \Omega_{i,j}^{(1,1)} \quad \text{and} \quad \Delta_{i,j}^{(2)}(T) = \frac{16}{5} \sqrt{\frac{2m_{i,j}}{\pi RT}} \pi \Omega_{i,j}^{(2,2)}, \tag{30}$$

with:

$$m_{i,j} = M_i M_j / (M_i + M_j), \tag{31}$$

being the reduced molecular mass. These integrals are given in m.s. With the definition of the modified collision integrals to species i and j, it is possible to define the mixture transport properties (viscosity and thermal conductivities) and the species diffusion property (diffusion coefficient).

2.3.3 Mixture molecular viscosity

[4] define the mixture molecular viscosity as:

$$\mu_{\text{mixt}} = \sum_{i=1}^{ns} \frac{m_i \sigma_i}{\sum_{j=1}^{ns} \sigma_j \Delta_{i,j}^{(2)}(T)}, \tag{32}$$

where:

$$m_i = M_i / N_{AV}, \tag{33}$$

being the mass of a species particle under study; $N_{AV} = 6.022045 \times 10^{23}$ particles/g-mol, Avogadro number.

This mixture molecular viscosity is given in kg/(m.s).

2.3.4 Vibrational, frozen, rotational and translational thermal conductivities

All thermal conductivities are expressed in J/(m.s.K). [4] defines the mixture vibrational, rotational and translational thermal conductivities, as also the species diffusion coefficient, as follows.

(a) Translational thermal conductivity:

The mode of translational internal energy is admitted completely excited; hence, the thermal conductivity of the translational internal energy is determined by:

$$k_T = \frac{15}{4} k_{\text{Boltzmann}} \sum_{i=1}^{ns} \frac{\sigma_i}{\sum_{j=1}^{ns} \bar{a}_{i,j} \sigma_j \Delta_{i,j}^{(2)}(T)}, \tag{34}$$

in which:

$k_{\text{Boltzmann}}$ = Boltzmann constant = $1,380622 \times 10^{-23}$ J/K;

$$\bar{a}_{i,j} = 1 + \frac{(1 - M_i/M_j)[0.45 - 2.54(M_i/M_j)]}{(1 + M_i/M_j)^2}. \tag{35}$$

(b) Rotational thermal conductivity:

The mode of rotational internal energy is also considered fully excited; hence, the thermal conductivity due to rotational internal energy is defined by:

$$k_R = k_{\text{Boltzmann}} \sum_{i=\text{mol}} \frac{\sigma_i}{\sum_{j=1}^{ns} \sigma_j \Delta_{i,j}^{(1)}(T)}. \tag{36}$$

(c) Frozen thermal conductivity:

$$k_f = k_T + k_R. \tag{37}$$

(d) Thermal conductivity due to molecular vibration:

The mode of vibrational internal energy, however, is assumed be partially excited; hence, the vibrational thermal conductivity is calculated according to [3] by:

$$k_v = k_{\text{Boltzmann}} \sum_{i=\text{mol}} \frac{(C_{v,v,i}/R) \sigma_i}{\sum_{j=1}^{ns} \sigma_j \Delta_{i,j}^{(1)}(T)}, \tag{38}$$

with $C_{v,v,i}$ obtained from Eq. (21).

2.3.5 Species diffusion coefficient

The mass-diffusion-effective coefficient, D_i , of the species “i” in the gaseous mixture is defined by:

$$D_i = \frac{\sigma^2 M_i (1 - \sigma_i M_i)}{\sum_{j=1}^{ns} \sigma_j / D_{i,j}} \quad \text{and} \quad D_{i,j} = \frac{k_{\text{Boltzmann}} T}{p \Delta_{i,j}^{(1)}(T)}, \quad (39)$$

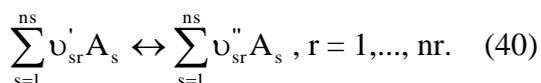
where: $D_{i,j}$ is the binary diffusion coefficient to a pair of particles of the species “i” and “j” and is related with the modified collision integral conform described above, in Eq. (39). This coefficient is measured in m^2/s .

2.4 Chemical Model

The chemical model employed to the case of thermochemical non-equilibrium is the same employed to the case of thermal equilibrium and chemical non-equilibrium (see [21-22]). The unique difference is in the calculation of the species production rates, where a temperature of reaction rate control is introduced in the place of the translational/rotational temperature, which is employed in the calculation of such rates in the thermal equilibrium and chemical non-equilibrium case. This procedure aims a couple between vibration and dissociation. This temperature is defined as: $T_{\text{rc}} = \sqrt{T \times T_v}$, where T is the translational/rotational temperature and T_v is the vibrational temperature. This temperature T_{rc} replaces the translational/rotational temperature in the calculation of the species production rates, according to [25].

2.4.1 Law of Mass Action

The symbolic representation of a given reaction in the present work follows the [26] formulation and is represented by:



The law of mass action applied to this system of chemical reactions is defined by:

$$\dot{\omega}_s = M_s \sum_{r=1}^{\text{nr}} (\nu_{\text{sr}}'' - \nu_{\text{sr}}') \left\{ k_{\text{fr}} \prod_{s=1}^{ns} \left(\frac{\rho_s}{M_s} \right)^{\nu_{\text{sr}}'} - k_{\text{br}} \prod_{s=1}^{ns} \left(\frac{\rho_s}{M_s} \right)^{\nu_{\text{sr}}''} \right\}, \quad (41)$$

where A_s represents the chemical symbol of species “s”, “ns” is the number of species of the present study (reactants and products) involved in the considered reaction; “nr” is the number of reactions

considered in the chemical model; ν_{sr}' e ν_{sr}'' are the stoichiometric coefficients to reactants and products, respectively; $k_{\text{fr}} = AT^B e^{-C/T}$ and $k_{\text{br}} = DT^{-E}$, with A, B, C, D and E being constants of a specific chemical reaction under study [“fr” = forward reaction and “br” = backward reaction].

Table 4. Chemical reactions and forward coefficients.

Reaction	Forward reaction rate coefficients, k_{fr} , $\text{cm}^3/(\text{mol.s})$	Third body
$\text{O}_2 + \text{M} \leftrightarrow 2\text{O} + \text{M}$	$3.61 \times 10^{18} T^{-1.0} e^{(-59,400/T)}$	O, N, O_2 , N_2 , NO
$\text{N}_2 + \text{M} \leftrightarrow 2\text{N} + \text{M}$	$1.92 \times 10^{17} T^{-0.5} e^{(-113,100/T)}$	O, O_2 , N_2 , NO
$\text{N}_2 + \text{N} \leftrightarrow 2\text{N} + \text{N}$	$4.15 \times 10^{22} T^{-0.5} e^{(-113,100/T)}$	-
$\text{NO} + \text{M} \leftrightarrow \text{N} + \text{O} + \text{M}$	$3.97 \times 10^{20} T^{-1.5} e^{(-75,600/T)}$	O, N, O_2 , N_2 , NO
$\text{NO} + \text{O} \leftrightarrow \text{O}_2 + \text{N}$	$3.18 \times 10^9 T^{-1.0} e^{(-19,700/T)}$	-
$\text{N}_2 + \text{O} \leftrightarrow \text{NO} + \text{N}$	$6.75 \times 10^{13} e^{(-37,500/T)}$	-

Table 5. Chemical reactions and backward coefficients.

Reaction	Backward reaction rate coefficients, k_{br} , $\text{cm}^3/(\text{mol.s})$ or $\text{cm}^6/(\text{mol}^2.\text{s})$	Third body
$\text{O}_2 + \text{M} \leftrightarrow 2\text{O} + \text{M}$	$3.01 \times 10^{15} T^{-0.5}$	O, N, O_2 , N_2 , NO
$\text{N}_2 + \text{M} \leftrightarrow 2\text{N} + \text{M}$	$1.09 \times 10^{16} T^{-0.5}$	O, O_2 , N_2 , NO
$\text{N}_2 + \text{N} \leftrightarrow 2\text{N} + \text{N}$	$2.32 \times 10^{21} T^{-0.5}$	-
$\text{NO} + \text{M} \leftrightarrow \text{N} + \text{O} + \text{M}$	$1.01 \times 10^{20} T^{-1.5}$	O, N, O_2 , N_2 , NO
$\text{NO} + \text{O} \leftrightarrow \text{O}_2 + \text{N}$	$9.63 \times 10^{11} T^{0.5} e^{(-3,600/T)}$	-
$\text{N}_2 + \text{O} \leftrightarrow \text{NO} + \text{N}$	1.5×10^{13}	-

It is important to note that $k_{br} = k_{fr}/k_{er}$, with k_{er} being the equilibrium constant which depends only of the thermodynamic quantities. In this work, $ns = 5$ and $nr = 17$. Table 4 presents the values to A, B, C, D and E for the forward reaction rates of the 17 chemical reactions. Table 5 presents the values to A, B, C, D and E for the backward reaction rates.

2.5 Vibrational Model

The vibrational internal energy of a molecule, in J/kg, is defined by:

$$e_{v,s} = \frac{R_s \theta_{v,s}}{e^{\theta_{v,s}/T_v} - 1}, \quad (42)$$

obtained by the integration of Eq. (21), and the vibrational internal energy of all molecules is given by:

$$e_v = \sum_{s=\text{mol}} c_s e_{v,s}. \quad (43)$$

The heat flux due to translational-vibrational relaxation, according to [27], is given by:

$$q_{T-v,s} = \rho_s \frac{e_{v,s}^*(T) - e_{v,s}(T_v)}{\tau_s}, \quad (44)$$

where: $e_{v,s}^*$ is the vibrational internal energy calculated at the translational temperature to the species "s"; and τ_s is the translational-vibrational relaxation time to the molecular species, in s. The relaxation time is the time of energy exchange between the translational and vibrational molecular modes.

2.5.1 Vibrational characteristic time of [28]

According to [28], the relaxation time of molar average of [29] is described by:

$$\tau_s = \tau_s^{M-W} = \frac{\sum_{l=1}^{ns} X_l}{\sum_{l=1}^{ns} X_l / \tau_{s,l}^{M-W}}, \quad (45)$$

with:

$\tau_{s,l}^{M-W}$ is the relaxation time between species of [29];

τ_s^{M-W} is the vibrational characteristic time of [29];

$$X_l = c_l / (N_{AV} m_l) \quad \text{and} \quad m_l = M_l / N_{AV}. \quad (46)$$

2.5.2 Definition of $\tau_{s,l}^{M-W}$:

For temperatures inferior to or equal to 8,000 K, [29] give the following semi-empirical correlation to the vibrational relaxation time due to inelastic collisions:

$$\tau_{s,l}^{M-W} = \left(\frac{B}{p_l} \right) e^{[A_{s,l}(T^{-1/3} - 0.015\mu_{s,l}^{1/4}) - 18.42]}, \quad (47)$$

where:

$$B = 1.013 \times 10^5 \text{Ns/m}^2 \quad ([30]);$$

p_l is the partial pressure of species "l" in N/m²;

$$A_{s,l} = 1.16 \times 10^{-3} \mu_{s,l}^{1/2} \theta_{v,s}^{4/3} \quad ([30]); \quad (48)$$

$$\mu_{s,l} = \frac{M_s M_l}{M_s + M_l}, \quad (49)$$

being the reduced molecular mass of the collision partners: kg/kg-mol;

T and $\theta_{v,s}$ in Kelvin.

2.5.3 [25] correction time

For temperatures superiors to 8,000 K, the Eq. (43) gives relaxation times less than those observed in experiments. To temperatures above 8,000 K, [25] suggests the following relation to the vibrational relaxation time:

$$\tau_s^P = \frac{1}{\xi_s \sigma_v n_s}, \quad (50)$$

where:

$$\xi_s = \sqrt{\frac{8R_s T}{\pi}}, \quad (51)$$

being the molecular average velocity in m/s;

$$\sigma_v = 10^{-20} \left(\frac{50,000}{T} \right)^2, \quad (52)$$

being the effective collision cross-section to vibrational relaxation in m²; and

$$n_s = \rho_s / m_s, \quad (53)$$

being the density of the number of collision particles of species “s”. ρ_s in kg/m^3 and m_s in kg/particle , defined by Eq. (33).

Combining the two relations, the following expression to the vibrational relaxation time is obtained:

$$\tau_s = \tau_s^{M-W} + \tau_s^P. \quad (54)$$

[25] emphasizes that this expression [Eq. (54)] to the vibrational relaxation time is applicable to a range of temperatures much more vast.

3 Structured [17] Algorithm to Thermochemical Non-Equilibrium

Considering the two-dimensional and structured case, the algorithm follows that described in [22], considering, however, the vibrational contribution ([31]) and the version of the two-temperature model to the frozen speed of sound [Eq. (23)]. Hence, the discrete-dynamic-convective flux is defined by:

$$R_{i+1/2,j} = |S|_{i+1/2,j} \left\{ \frac{1}{2} M_{i+1/2,j} \left[\begin{pmatrix} \rho a \\ \rho a u \\ \rho a v \\ \rho a H \end{pmatrix}_L + \begin{pmatrix} \rho a \\ \rho a u \\ \rho a v \\ \rho a H \end{pmatrix}_R \right] - \frac{1}{2} \phi_{i+1/2,j} \left[\begin{pmatrix} \rho a \\ \rho a u \\ \rho a v \\ \rho a H \end{pmatrix}_R - \begin{pmatrix} \rho a \\ \rho a u \\ \rho a v \\ \rho a H \end{pmatrix}_L \right] \right\} + \begin{pmatrix} 0 \\ S_x p \\ S_y p \\ 0 \end{pmatrix}_{i+1/2,j}, \quad (55)$$

the discrete-chemical-convective flux is defined by:

$$R_{i+1/2,j} = |S|_{i+1/2,j} \left\{ \frac{1}{2} M_{i+1/2,j} \left[\begin{pmatrix} \rho_1 a \\ \rho_2 a \\ \rho_4 a \\ \rho_5 a \end{pmatrix}_L + \begin{pmatrix} \rho_1 a \\ \rho_2 a \\ \rho_4 a \\ \rho_5 a \end{pmatrix}_R \right] - \frac{1}{2} \phi_{i+1/2,j} \left[\begin{pmatrix} \rho_1 a \\ \rho_2 a \\ \rho_4 a \\ \rho_5 a \end{pmatrix}_R - \begin{pmatrix} \rho_1 a \\ \rho_2 a \\ \rho_4 a \\ \rho_5 a \end{pmatrix}_L \right] \right\}, \quad (56a)$$

$$- \frac{1}{2} \phi_{i+1/2,j} \left[\begin{pmatrix} \rho_1 a \\ \rho_2 a \\ \rho_4 a \\ \rho_5 a \end{pmatrix}_R - \begin{pmatrix} \rho_1 a \\ \rho_2 a \\ \rho_4 a \\ \rho_5 a \end{pmatrix}_L \right], \quad (56b)$$

and the discrete-vibrational-convective flux is determined by:

$$R_{i+1/2,j} = |S|_{i+1/2,j} \left\{ \frac{1}{2} M_{i+1/2,j} [(\rho e_v a)_L + (\rho e_v a)_R] - \frac{1}{2} \phi_{i+1/2,j} [(\rho e_v a)_R - (\rho e_v a)_L] \right\}. \quad (57)$$

The same definitions presented in [21-22] are valid to this algorithm. The time integration is performed employing the Runge-Kutta explicit method of five stages, second-order accurate, to the three types of convective flux. To the dynamic part, this method can be represented in general form by:

$$\begin{aligned} Q_{i,j}^{(0)} &= Q_{i,j}^{(n)} \\ Q_{i,j}^{(k)} &= Q_{i,j}^{(0)} - \alpha_k \Delta t_{i,j} R(Q_{i,j}^{(k-1)}) / V_{i,j}, \\ Q_{i,j}^{(n+1)} &= Q_{i,j}^{(k)} \end{aligned} \quad (58)$$

to the chemical part, it can be represented in general form by:

$$\begin{aligned} Q_{i,j}^{(0)} &= Q_{i,j}^{(n)} \\ Q_{i,j}^{(k)} &= Q_{i,j}^{(0)} - \alpha_k \Delta t_{i,j} [R(Q_{i,j}^{(k-1)}) / V_{i,j} - S_C(Q_{i,j}^{(k-1)})], \\ Q_{i,j}^{(n+1)} &= Q_{i,j}^{(k)} \end{aligned} \quad (59)$$

where the chemical source term S_C is calculated with the temperature T_{irc} . Finally, to the vibrational part:

$$\begin{aligned} Q_{i,j}^{(0)} &= Q_{i,j}^{(n)} \\ Q_{i,j}^{(k)} &= Q_{i,j}^{(0)} - \alpha_k \Delta t_{i,j} [R(Q_{i,j}^{(k-1)}) / V_{i,j} - S_v(Q_{i,j}^{(k-1)})], \\ Q_{i,j}^{(n+1)} &= Q_{i,j}^{(k)} \end{aligned} \quad (60)$$

in which:

$$S_v = \sum_{s=\text{mol}} q_{T-v,s} + \sum_{s=\text{mol}} S_{C,s} e_{v,s}; \quad (61)$$

$k = 1, \dots, 5$; $\alpha_1 = 1/4$, $\alpha_2 = 1/6$, $\alpha_3 = 3/8$, $\alpha_4 = 1/2$ and $\alpha_5 = 1$. This scheme is first-order accurate in space and second-order accurate in time. The second-order of spatial accuracy is obtained by the "MUSCL" procedure (details in [32]).

The [17] scheme in its first-order two-dimensional unstructured version to an ideal gas formulation is presented in [33]. The extension to reactive flow in thermochemical non-equilibrium can be deduced from the present code.

The viscous formulation follows that of [34], which adopts the Green theorem to calculate primitive variable gradients. The viscous vectors are obtained by arithmetical average between cell (i,j) and its neighbours. As was done with the convective terms, there is a need to separate the viscous flux in three parts: dynamical viscous flux, chemical viscous flux and vibrational viscous flux. The dynamical part corresponds to the first four equations of the Navier-Stokes ones, the chemical part corresponds to the following four equations and the vibrational part corresponds to the last equation. The spatially variable time step technique has provided excellent convergence gains as demonstrated in [18-19] and is implemented in the code presented in this work. Details in [18-19; 22].

4 Results

Tests were performed in three microcomputers: one with INTEL CELERON processor, 1.5 GHz of "clock" and 1.0 GBytes of RAM (notebook), the second with an AMD SEMPRON (tm) 2600+ processor, 1.83 GHz of "clock" and 512 MBytes of RAM (desktop) and the third with an INTEL CELERON processor, 2.13 GHz of "clock" and 1.0 GBytes of RAM (notebook). As the interest of this work is steady state problems, it is necessary to define a criterion which guarantees the convergence of the numerical results. The criterion adopted was to consider a reduction of no minimal four (4) orders of magnitude in the value of the maximum residual in the calculation domain, a typical CFD-community criterion. The residual of each cell was defined as the numerical value obtained from the discretized conservation equations. As there are nine (9) conservation equations to each cell, the maximum value obtained from these equations is defined as the residual of this cell. Hence, this residual is compared with the residual of the other cells, calculated of the same way, to define the maximum residual in the calculation domain. In the simulations, the attack angle was set equal to zero.

4.1 Initial and Boundary Conditions to the Studied Problem

The initial conditions are presented in Tab. 6. The Reynolds number is obtained from data of [35]. The boundary conditions to this problem of reactive flow are detailed in [24], as well the geometry in study, the meshes employed in the simulations and the description of the computational configuration.

Table 6 Initial conditions to the problem of the blunt body.

Property	Value
M_∞	8.78
ρ_∞	0.00326 kg/m ³
p_∞	687 Pa
U_∞	4,776 m/s
T_∞	694 K
$T_{v,\infty}$	694 K
altitude	40,000 m
c_N	10 ⁻⁹
c_O	0.07955
c_{O_2}	0.13400
c_{NO}	0.05090
L	2.0 m
Re_∞	2.3885x10 ⁶

The geometry is a blunt body with 1.0 m of nose ratio and parallel rectilinear walls. The far field is located at 20.0 times the nose ratio in relation to the configuration nose. The dimensionless employed in the Euler and Navier-Stokes equations in this study are also described in [24].

4.2 Studied Cases

Table 7 presents the studied cases in this work, the mesh characteristics and the order of accuracy of the [17] scheme.

Table 7 Studied cases, mesh characteristics and accuracy order.

Case	Mesh	Accuracy Order
Inviscid – 2D	63x60	First ^a
Viscous – 2D	63x60 (7.5%) ^c	First ^a
Inviscid – 2D	63x60	Second ^a
Viscous – 2D	63x60 (7.5%)	Second ^a
Inviscid – 2D	63x60	First ^b
Viscous – 2D	63x60 (7.5%)	First ^b

^a Structured spatial discretization; ^b Unstructured spatial discretization; ^c Exponential stretching..

4.3 Results in Thermochemical Non-Equilibrium

4.3.1 Inviscid, structured and first-order accurate case

Figure 1 exhibits the pressure contours around the blunt body geometry calculated at the computational domain by the [17] scheme, in its first-order version, in thermochemical non-equilibrium. The non-dimensional pressure peak is equal to 148 unities and is located at the configuration nose. The solution presents good symmetry characteristics. Figure 2 shows the Mach number contours calculated at the computational domain. A region of subsonic flow is formed behind the normal shock wave, at the geometry nose. The shock wave develops normally: normal shock wave at the configuration nose, decaying to oblique shock waves and finally reaching, far from the blunt body, the Mach wave.

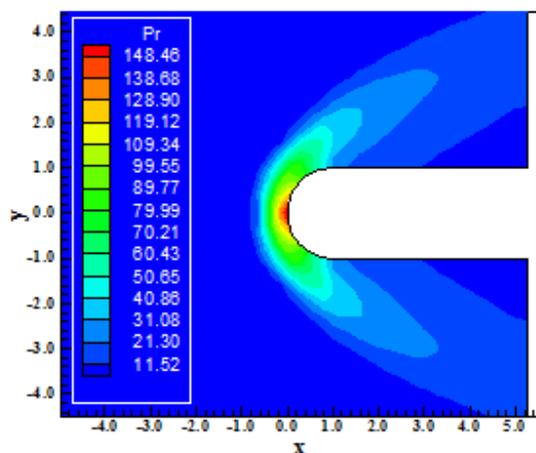


Fig. 1 Pressure contours.

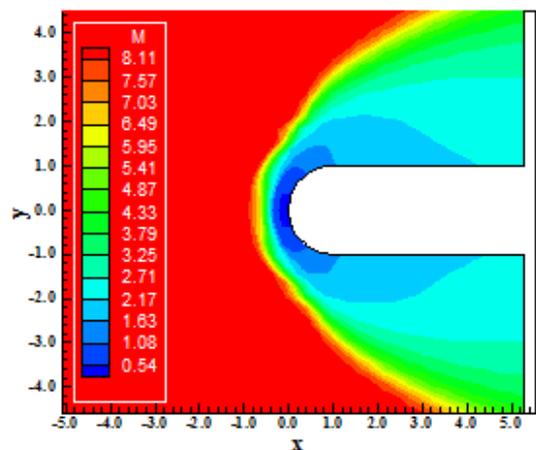


Fig. 2 Mach number contours.

Figure 3 presents the contours of the translational/rotational temperature distribution calculated at the computational domain. The translational/rotational temperature reaches a peak of 8,105 K at the configuration nose and determines an appropriated region to dissociation of N_2 and O_2 . Along the blunt body, the translational/rotational temperature assumes an approximated value of 6,000 K, what also represents a good value to the dissociation firstly of O_2 and, in second place, of the N_2 .

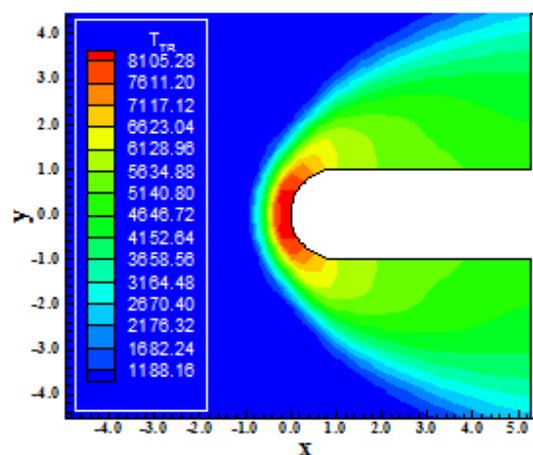


Fig. 3 T/R temperature contours.

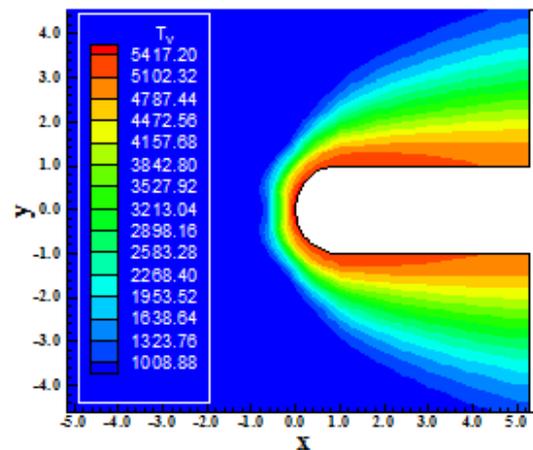


Fig. 4 Vibrational temperature contours.

Figure 4 exhibits the contours of the vibrational temperature calculated at the two-dimensional computational domain. Its peak reaches a value of 5,417 K and also contributes to the dissociation of N_2 and O_2 , since the employed temperature to the calculation of the forward and backward reaction rates (reaction-rate-control temperature, T_{rc}) in the thermochemical non-equilibrium is equal to $\sqrt{T \cdot T_v}$, the square root of the product between the translational/rotational temperature and the

vibrational temperature. Hence, the effective temperature to the calculation of the chemical phenomena guarantees the couple between the vibrational mode and the dissociation reactions. In this configuration nose region, the temperature T_{irc} reaches, in the steady state condition, the approximated value of 6,626 K, guaranteeing that the dissociation phenomena described above occurs. Good symmetry characteristics are observed.

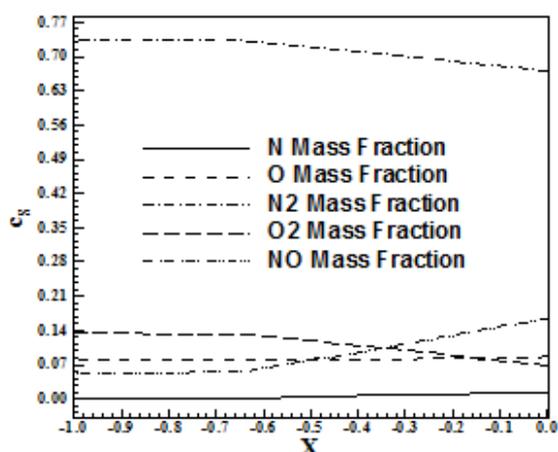


Fig. 5 Mass fraction distribution at the blunt body stagnation line.

Figure 5 shows the mass fraction distribution of the five chemical species under study, namely: N, O, N₂, O₂ and NO, along the geometry stagnation line or geometry symmetry line. As can be observed from this figure, enough dissociation of N₂ and O₂ occur, with the consequent meaningful increase of N, of NO and of O in the gaseous mixture. As mentioned early, this behaviour is expected due to the effective peak temperature reached at the calculation domain. The NO presented the biggest absolute increase in its formation, whereas the N presented the biggest relative increase.

4.3.2 Viscous, structured and first-order accurate case

Figure 6 exhibits the pressure contours to the viscous reactive flow around a blunt body, in two-dimensions, calculated at the computational domain. The non-dimensional pressure peak reaches 170 unities, more severe than that obtained with the inviscid case. The pressure field is also more severe in the viscous case than in the inviscid one. The shock is closer to the geometry due to the mesh exponential stretching and the viscous reactive effects of the simulation. The region of the pressure peak is also better defined. The solution presents good symmetry characteristics.

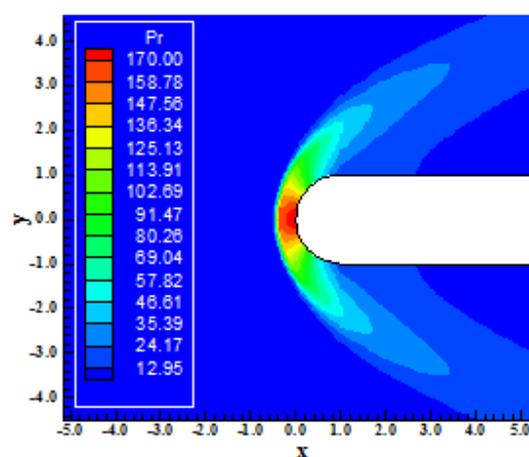


Fig. 6 Pressure contours.

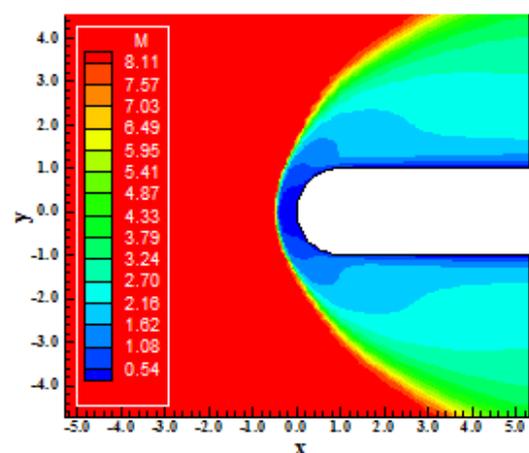


Fig. 7 Mach number contours.

Figure 7 shows the Mach number contours calculated at the computational domain. The subsonic flow region, which is formed behind the normal shock, is well captured and propagates by the lower and upper geometry walls, due to the transport phenomena considered in the viscous simulations. The shock wave presents the expected behaviour: normal shock wave at the configuration nose, oblique shock waves and a Mach wave far from de blunt body.

Figure 8 exhibits the distribution of the translational/rotational temperature calculated at the computational domain. The peak of translational/rotational temperature reaches the approximated value of 8,750 K at the configuration nose and this value is observed along the lower and upper surfaces of the geometry.

Figure 9 presents the vibrational temperature distribution calculated at the computational domain. Its peak, at the configuration nose, reaches an approximated value of 5,403 K. The effective

temperature to the calculation of the dissociation and recombination reactions, T_{rc} , is equal approximately to 6,876 K, which guarantees that processes of dissociation of O_2 and N_2 can be captured by the employed formulation. This value of effective temperature to the viscous reactive simulations is superior to that obtained in the inviscid case. Good symmetry characteristics are observed in these figures.

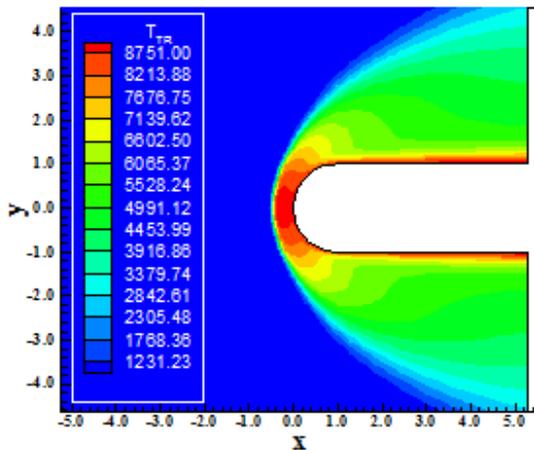


Fig. 8 T/R temperature contours.

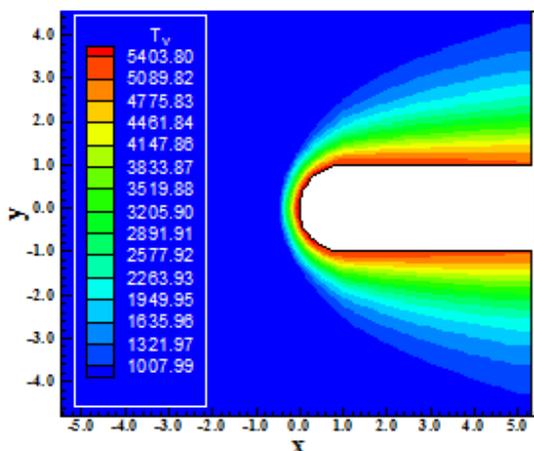


Fig. 9 Vibrational temperature contours.

Figure 10 exhibits the mass fraction distribution of the five chemical species under study along the geometry stagnation line. As can be observed, enough dissociation of the N_2 and O_2 occurs, with the consequent meaningful increase of the N, of the NO and of the O in the gaseous mixture. This behaviour is expected due to the temperature peak reached in the calculation domain. The biggest absolute increase in the formation of a species was due to the NO, while, in relative terms, was due to the N. As can also be noted, the mass fraction of the NO tends to assume a constant value at the

configuration nose. This is due to the same behaviour observed in the mass fraction distributions of the N and O, close to the configuration nose (constancy).

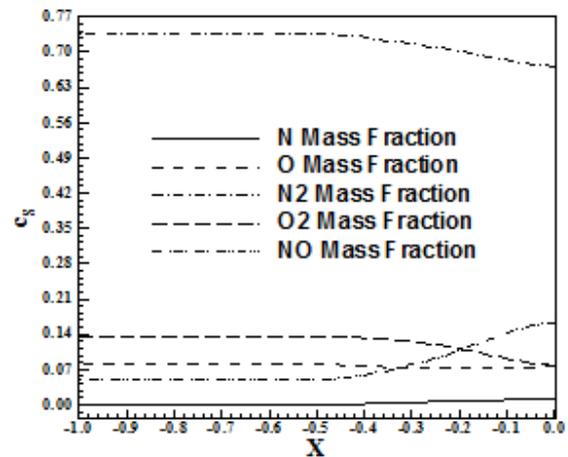


Fig. 10 Mass fraction distribution at the blunt body stagnation line.

4.3.3 Inviscid, structured and second-order accurate case

Figure 11 shows the pressure contours obtained by the inviscid simulation performed by the second-order [17] scheme employing a minmod non-linear flux limiter. The non-dimensional pressure peak is approximately equal to 142 unities, slightly inferior to the respective peak obtained by the first-order solution. This pressure peak occurs at the configuration nose. The solution presents good symmetry characteristics. Figure 12 presents the Mach number contours obtained at the computational domain. The subsonic region which is formed behind the normal shock wave is well characterized at the configuration nose.

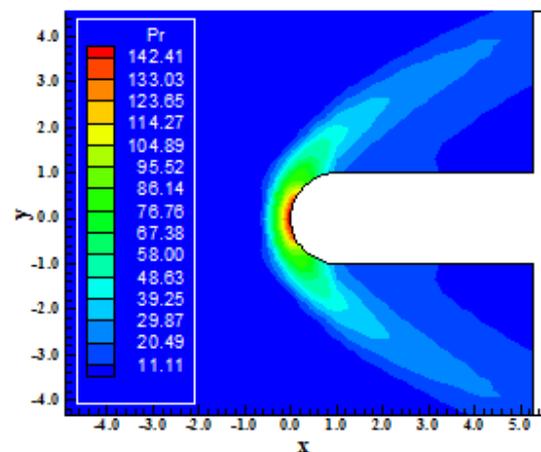


Fig. 11 Pressure contours.

Good symmetry characteristics are observed. The shock wave presents the expected behaviour, passing from a normal shock at the configuration stagnation line to a Mach wave far from the blunt body.

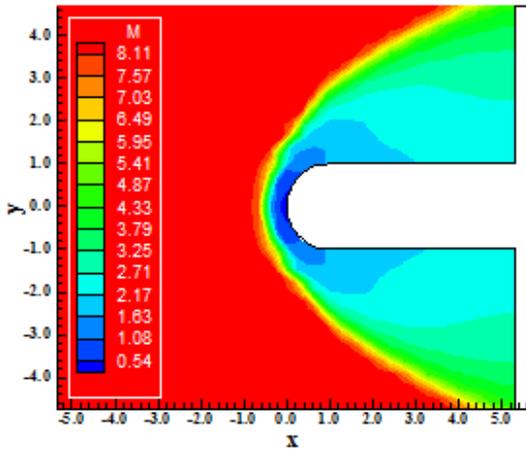


Fig. 12 Mach number contours.

Figure 13 exhibits the contours of the translational/rotational temperature distribution calculated at the computational domain. The translational/rotational temperature peak occurs at the configuration nose and is approximately equal to 7,922 K. Figure 14 presents the contours of the vibrational temperature distribution calculated at the computational domain. The vibrational temperature peak is approximately equal to 5,028 K and is observed at the configuration nose. The effective temperature to calculation of the reaction rates (reaction rate control temperature, T_{rc}) is approximately equal to 6,311 K, which represents a temperature capable to capture the dissociation phenomena of N_2 and O_2 . Good symmetry characteristics are observed in both figures.

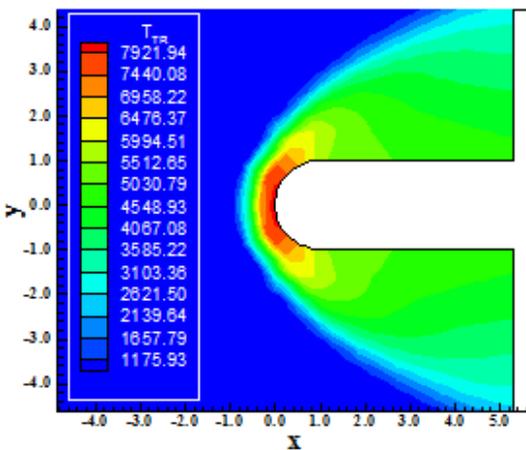


Fig. 13 T/R temperature contours.

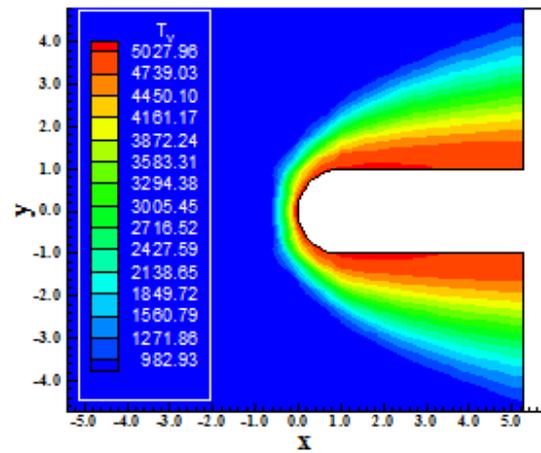


Fig. 14 Vibrational temperature contours.

Figure 15 exhibits the mass fraction distribution of the five chemical species under study, namely: N, O, N_2 , O_2 and NO, along the geometry stagnation line. As can be observed, discrete dissociation of N_2 and O_2 occur, with consequent discrete increase of the N, of the NO and of the O in the gaseous mixture. This behaviour is expected due to the effective temperature peak reached at the computational domain to the calculation of thermochemical non-equilibrium and to a second-order numerical formulation, which behaves in a more conservative way (see [22]), providing minor dissociation of N_2 and O_2 .

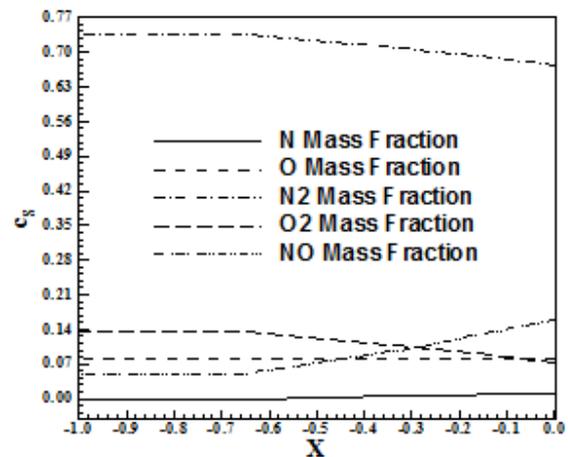


Fig. 15 Mass fraction distribution at the blunt body stagnation line.

4.3.4 Viscous, structured and second-order accurate case

Figure 16 exhibits the pressure contours calculated at the computational domain to the studied configuration of blunt body. The non-dimensional pressure peak is approximately equal to 164 unities,

less than the respective value obtained by the first-order solution. The shock is positioned closer to the blunt body due to the mesh stretching and the employed-viscous-reactive formulation. Good symmetry characteristics are observed. Figure 17 shows the Mach number contours obtained at the computational domain. The subsonic region behind the normal shock wave, at the stagnation line, is well captured by the solution. This region propagates along the lower and upper surfaces of the geometry, due to the transport phenomena (viscosity, thermal conductivity and species diffusion). The shock wave behaviour is also the expected: normal shock at the geometry nose, oblique shock waves close to the configuration and Mach wave far from the geometry.

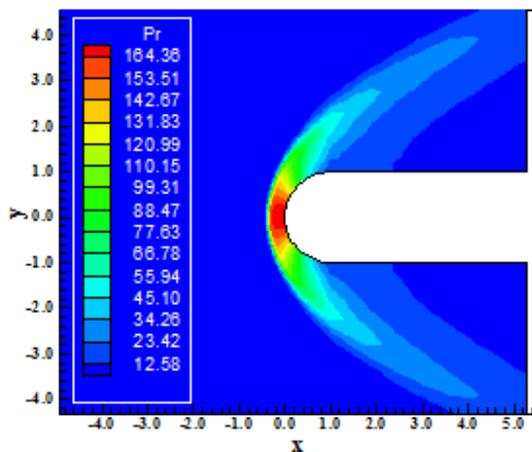


Fig. 16 Pressure contours.

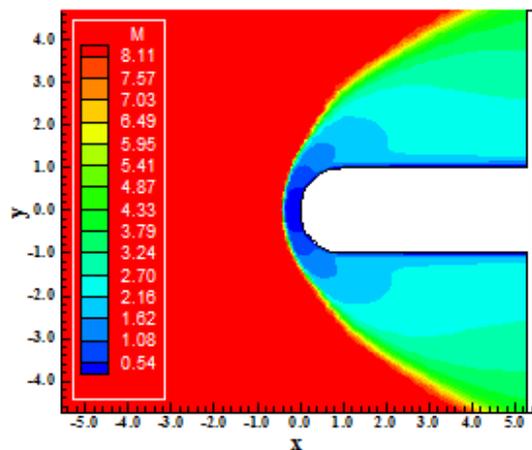


Fig. 17 Mach number contour.

Figure 18 exhibits the translational/rotational temperature distribution calculated at the computational domain. The temperature peak at the configuration nose reaches approximately 8,493 K. Figure 19 shows the vibrational temperature

distribution calculated at the computational domain. The temperature peak at the nose and along the lower and upper surfaces of the geometry is equal to 5,904 K. The effective temperature to the calculation of the reaction rates, T_{TRC} , was of 7,081 K, superior to that obtained with the first-order solution, which is representative to the calculation of the N_2 and O_2 dissociations. Both Figs. 18 and 19 exhibit good symmetry characteristics.

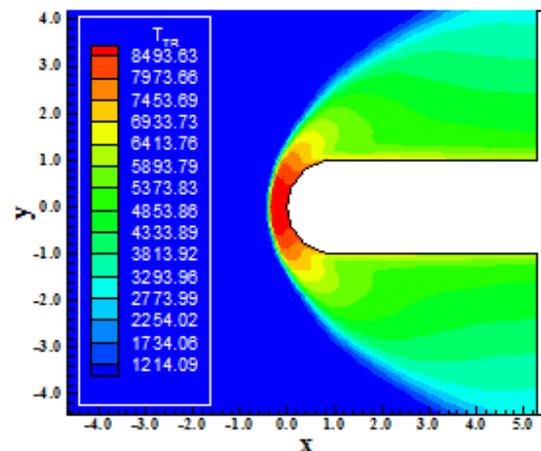


Fig. 18 T/R temperature contours.

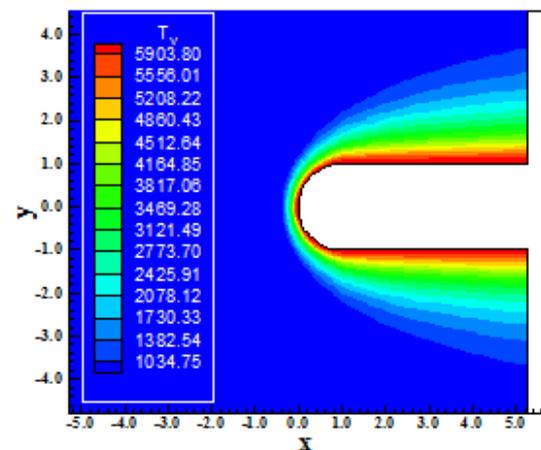


Fig. 19 Vibrational temperature contours.

Figure 20 presents the mass fraction distribution of the five chemical species under study, namely: N, O, N_2 , O_2 and NO, along the geometry stagnation line. As can be observed, good dissociation of N_2 and O_2 occur, with consequent good increase of N, O and NO in the gaseous mixture. This behaviour is expected due to the effective temperature peak reached at the computational domain to the calculation of thermochemical non-equilibrium and to a second-order numerical formulation, which behaves in a more conservative way ([22]), providing major dissociation of N_2 and O_2 . In other

words, this solution provided by the second-order [17] scheme, as seen in other cases, tends to provide bigger dissociation of N_2 and O_2 . As this solution is more precise (second-order), it should be considered as standard to comparison with other schemes.

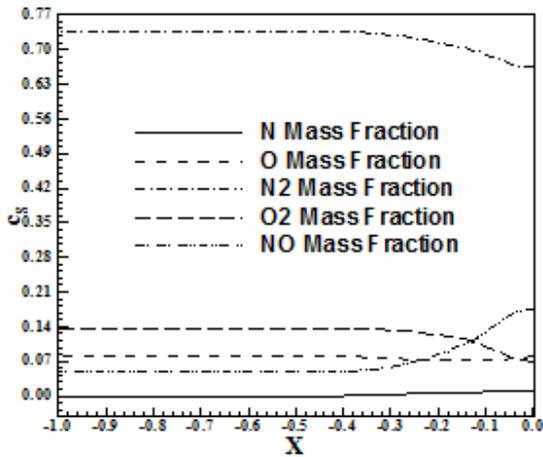


Fig. 20 Mass fraction distribution at the blunt body stagnation line.

4.3.5 Inviscid, unstructured and first-order accurate case

Figure 21 exhibits the pressure contours obtained to the problem of the blunt body, with unstructured spatial discretization, in two-dimensions. The non-dimensional pressure peak is approximately equal to 135 unities, inferior to that obtained with the first-order structured solution. The pressure peak occurs at the configuration nose.

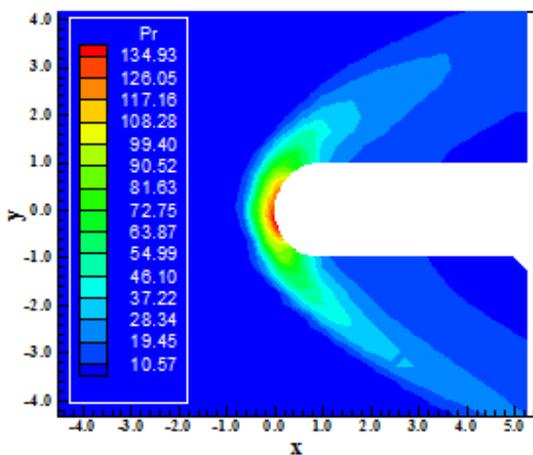


Fig. 21 Pressure contours.

The pressure field is less severe than that obtained with the first-order structured solution. The non-symmetry in the pressure field is meaningful, although typical of unstructured solutions. Figure 22 shows the Mach number contours calculated at the

computational domain. The subsonic flow region behind the normal shock wave is well characterized. The behaviour of the shock wave is the expected: normal shock at the stagnation line, oblique shock waves close to the blunt body and Mach wave far from the body. The Mach number contours present meaningful non-symmetries, as expected.

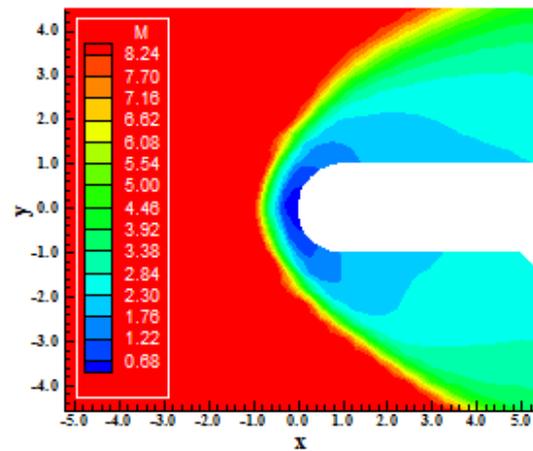


Fig. 22 Mach number contour.

Figure 23 presents the translational/rotational temperature distribution calculated at the computational domain. The translational/rotational temperature peak is approximately equal to 8,537 K and is located at the configuration nose.

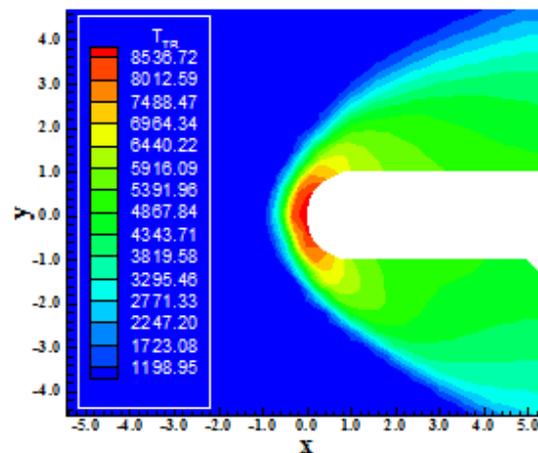


Fig. 23 T/R temperature contours.

Figure 24 exhibits the vibrational temperature distribution calculated at the computational domain. The vibrational temperature peak occurs at the configuration nose and its value is approximately 2,317 K. The effective temperature to the calculation of the direct and inverse reaction rates of the adopted chemical model is approximately equal to 4,447 K, inferior to that obtained with the first-

order structured solution, guaranteeing, however, that dissociation reactions of N_2 and O_2 be well captured. Figures 23 and 24 present non-symmetries in the solution, as expected.

symmetry characteristics are better than those observed in the inviscid case. It is due to the mesh stretching, which allows to a better mesh refinement.

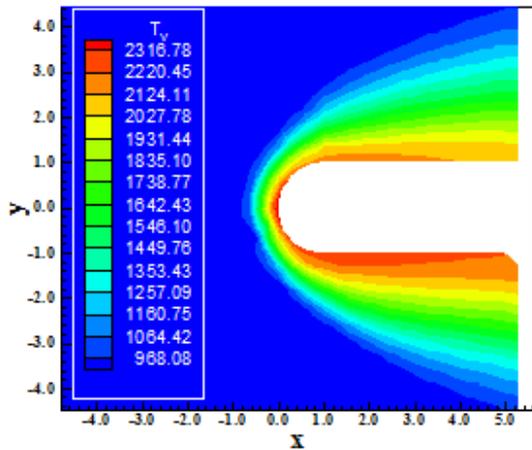


Fig. 24 Vibrational temperature contours.

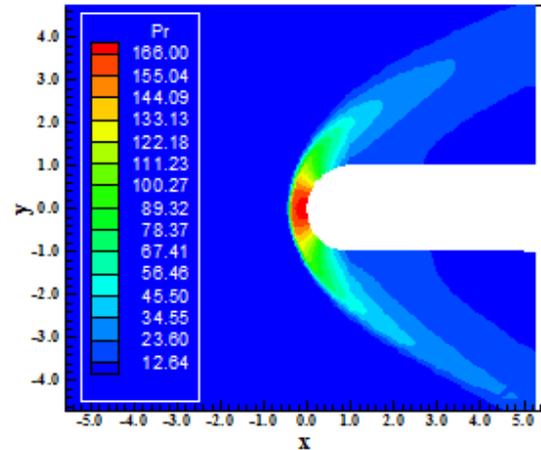


Fig. 26 Pressure contours.

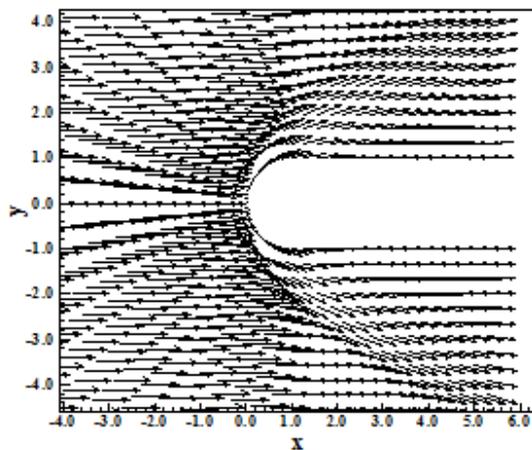


Fig. 25 Velocity vector field.

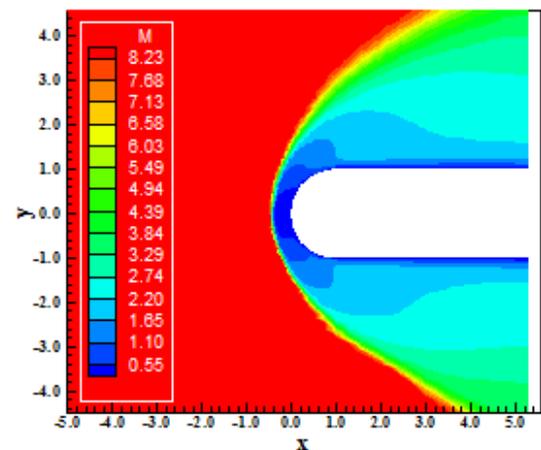


Fig. 27 Mach number contour.

Finally, Fig. 25 shows the velocity vector field to the first-order unstructured case according to an inviscid formulation. As can be noted, the tangency condition is fully satisfied by the inviscid formulation.

4.3.6 Viscous, unstructured and first-order accurate case

Figure 26 shows the pressure contours obtained at the computational domain to the viscous blunt body problem. The non-dimensional pressure peak reaches the approximated value of 166 unities, inferior to the respective one obtained with the first-order viscous structured solution. The pressure peak is established at the configuration nose and the pressure field is less severe than the respective one obtained by the first-order structured solution. The

Figure 27 exhibits the Mach number contours calculated at the computational domain. The region of subsonic flow established behind the normal shock wave accords to the theory and propagates along the lower and upper blunt body surfaces, due to the transport phenomena considered in the viscous formulation. The shock wave normally develops: normal shock wave at the configuration nose, oblique shock waves along the blunt body and Mach wave far from the geometry. Again, the symmetry characteristics are better than their inviscid contra part.

Figure 28 presents the translational/rotational temperature distribution calculated at the computational domain. The translational/rotational temperature peak at the calculation domain reaches an approximately value of 9,232 K.

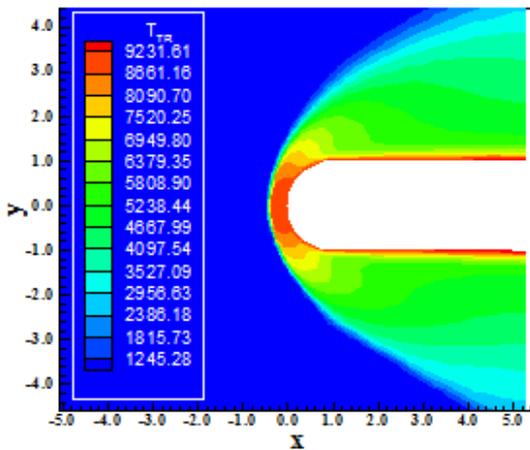


Fig. 28 T/R temperature contours.

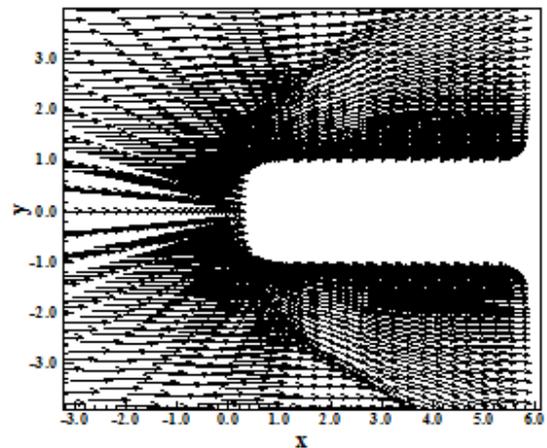


Fig. 30 Velocity vector field.

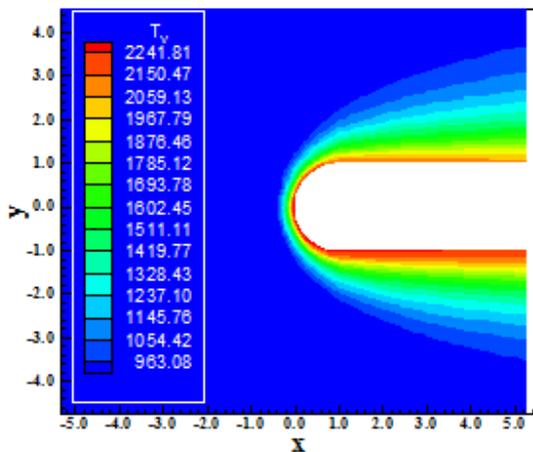


Fig. 29 Vibrational temperature contours.

Figure 29 exhibits the vibrational temperature distribution calculated at the computational domain. The peak of vibrational temperature at the calculation domain reaches the approximated value of 2,242 K. With it, the effective temperature, T_{trc} , to the calculation of the direct and inverse reaction rates of the adopted chemical model assumes the approximated value of 4,550 K, which still allows a meaningful dissociation of N_2 and O_2 . This temperature is inferior to the respective obtained with the first-order structured solution, which allows to conclude that should occurs less formation of N, NO and O at the calculation domain of this solution than in the first-order viscous structured solution.

Figure 30 shows the velocity vector field to this first-order viscous unstructured solution. The flow adherence and non-permeability conditions around the geometry wall are fully satisfied by the adopted viscous formulation.

4.3.7 Shock Position

In this section is presented the behaviour of the shock position in ideal, in thermal equilibrium and chemical non-equilibrium, and in thermochemical non-equilibrium conditions. Only first-order solutions are compared because the second-order ideal gas solutions did not present converged ones.

The detached shock position in terms of pressure distribution, in the inviscid case and first-order accurate solution, is exhibited in Fig. 31. It is shown the ideal-gas-shock position, the thermal equilibrium and chemical non-equilibrium shock position ([22]), and the thermochemical non-equilibrium shock position. As can be observed, the ideal-gas-shock position is located at 1.30 m, whereas the thermal equilibrium and chemical non-equilibrium positions are located at 0.95 m. As referred in the CFD literature, in reactive flow the shock is closer to the configuration.

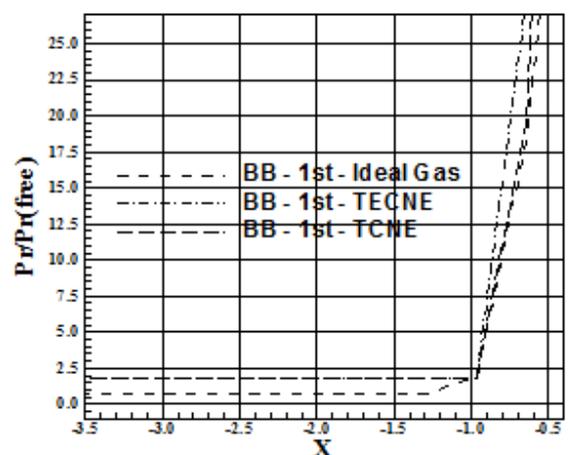


Fig. 31 Shock position (inviscid).

As can be observed in this inviscid solution, the reactive shocks are actually closer to the blunt body than the ideal shock.

The detached shock position in terms of pressure distribution, in the viscous case and first-order accurate solution, is exhibited in Fig. 32. It is shown the ideal-gas-shock position, the thermal equilibrium and chemical non-equilibrium shock position ([22]), and the thermochemical non-equilibrium shock position. As can be observed, the ideal-gas-shock position is located at 0.65 m, whereas the thermal equilibrium and chemical non-equilibrium and the thermochemical non-equilibrium positions are located at 0.52 m. As aforementioned, in reactive flow the shock is closer to the configuration. As can be observed in this viscous solution, the reactive shock is actually closer to the blunt body than the ideal shock.

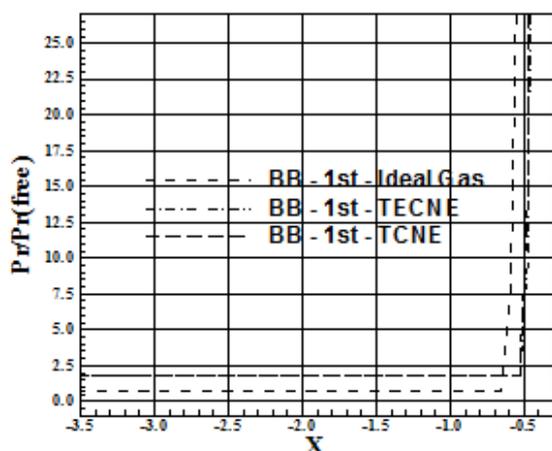


Fig. 32 Shock position (viscous).

4.3.8 Aerodynamic coefficients of lift and drag

Table 8 exhibits the aerodynamic coefficients of lift and drag obtained by the problem of the blunt body, with structured discretization, to the reactive formulation. Both reactive formulations of thermal equilibrium and chemical non-equilibrium ([22]) and thermochemical non-equilibrium are considered in this comparison. These coefficients are only due to the pressure term. The contribution of the friction term was not considered.

To the problem of the blunt body, a symmetric geometry in relation to the x axis, a zero value, or close to it, to the lift coefficient is expected. By Table 8, it is possible to note that the solution closest to this value to c_L was that of the [17] scheme with second-order accuracy, in an inviscid formulation, to a reactive condition of thermochemical non-equilibrium. In general, the values obtained to the thermochemical non-equilibrium case were better than those obtained by

the thermal equilibrium and chemical non-equilibrium case. The maximum c_D was obtained by the solution of the [17] scheme, first-order accurate, employing a viscous formulation and a condition of thermal equilibrium and chemical non-equilibrium.

Table 8 Aerodynamic coefficients of lift and drag to the structured blunt body case.

Studied case	c_L	c_D
First-Order/Inviscid/TECNE ⁽¹⁾	8.125×10^{-15}	1.167
First-Order/Viscous/TECNE	-2.626×10^{-16}	1.446
Second-Order/Inviscid/TECNE	1.072×10^{-10}	1.299
Second-Order/Viscous/TECNE	-2.754×10^{-15}	1.391
First-Order/Inviscid/TCNE ⁽²⁾	3.866×10^{-15}	1.284
First-Order/Viscous/TCNE	8.227×10^{-15}	1.438
Second-Order/Inviscid/TCNE	9.095×10^{-12}	1.330
Second-Order/Viscous/TCNE	-2.642×10^{-14}	1.390

⁽¹⁾ TECNE: Thermal Equilibrium and Chemical Non-Equilibrium; ⁽²⁾ TCNE: Thermal and Chemical Non-Equilibrium.

4.3.9 Quantitative Analysis

In terms of quantitative results, the present authors compared the reactive results with the perfect gas solutions. The stagnation pressure at the blunt body nose and the shock standoff distance were evaluated assuming the perfect gas formulation. Such parameters calculated at this way are not the best comparisons, but in the absence of practical reactive results, these constitute the best available results.

To calculate the stagnation pressure ahead of the blunt body, [36] presents in its B Appendix values of the normal shock wave properties ahead of the configuration. The ratio pr_0/pr_∞ is estimated as function of the normal Mach number and the stagnation pressure pr_0 can be determined from this parameter. Hence, to a freestream Mach number of 9.0 (close to 8.78), the ratio pr_0/pr_∞ assumes the

value 104.8. The value of pr_∞ is determined by the following expression:

$$pr_\infty = \frac{pr_{\text{initial}}}{\rho_{\text{initial}} \times a_{\text{initial}}^2} \quad (60)$$

In the present study, $pr_{\text{initial}} = 687 \text{ N/m}^2$, $\rho_{\text{initial}} = 0.004 \text{ kg/m}^3$ and $a_{\text{initial}} = 317.024 \text{ m/s}$. Considering these values, one concludes that $pr_\infty = 1.709$ (non-dimensional). Using the ratio obtained from [36], the stagnation pressure ahead of the configuration nose is estimated as 179.10 unities. Table 9 compares the values obtained from the simulations with this theoretical parameter and presents the numerical percentage errors. As can be observed, with exception of case 5, all other solutions present percentage errors equal or less than 20.5%, which is a reasonable estimation of the stagnation pressure.

Table 9 Comparisons between theoretical and numerical results.

Case	pr_0	Error (%)
Inviscid/Structured/1 st Order	148.46	17.11
Viscous/Structured/1 st Order	170.00	5.08
Inviscid/Structured/2 nd Order	142.41	20.49
Viscous/Structured/2 nd Order	164.36	8.23
Inviscid/Unstructured/1 st Order	134.93	24.66
Viscous/Unstructured/1 st Order	166.00	7.31

Another possibility to quantify the results is the determination of the shock standoff distance. [37] presents a graphic in which is plotted the shock standoff distance of a pre-determined configuration versus the Mach number. Considering the blunt body nose approximately as a cylinder and using the value 8.78 to the Mach number, it is possible to obtain the value 0.19 to the ratio δ/d , where δ is the position of the normal shock wave in relation to the body nose and d is a characteristic length of the configuration. In the present study, $d = 2.0 \text{ m}$ (diameter of the body nose) and $\delta = 0.38 \text{ m}$. Table 10 presents the values obtained by δ for the different cases and the percentage errors. This table shows that the best result is obtained with the structured, viscous, second order version of [17]. As the shock standoff distance presented in [37] is more realistic,

presenting smaller dependence of the perfect gas hypothesis, improved results were expected to obtain in this study. Hence, the best solution is obtained by the [17] scheme in its second order version.

Table 10 Shock standoff distance obtained from numerical schemes.

Case	δ_{NUM} (m)	Error (%)
Inviscid/Structured/1 st Order	0.90	136.84
Viscous/Structured/1 st Order	0.48	26.32
Inviscid/Structured/2 nd Order	0.63	65.79
Viscous/Structured/2 nd Order	0.41	7.89
Inviscid/Unstructured/1 st Order	0.80	110.53
Viscous/Unstructured/1 st Order	0.48	26.32

4.3.10 Computational performance of the studied algorithms

Table 11 presents the computational data of the reactive simulations performed with the [17] scheme to the problem of the blunt body in two-dimensions. The reactive simulations involved the thermal equilibrium and chemical non-equilibrium solutions obtained from [21] and the present thermochemical non-equilibrium results. In this table are exhibited the studied case, the maximum number of CFL employed in the simulation, the number of iterations to convergence and the number of orders of reduction in the magnitude of the maximum residual in relation to its initial value to convergence.

As can be observed, all test-cases converged with no minimal four orders of reduction in the value of the maximum residual. The maximum numbers of CFL presented the following distribution: 0.5 in four (4) cases (33.33%), 0.3 in two (2) cases (16.67%) and 0.1 in six (6) cases (50.00%). The convergence iterations did not overtake 7,800, in all studied cases. However, the time wasted in the simulations was much raised, taking until days to convergence (to four orders of reduction in the maximum residual). This aspect can be verified in the computational costs presented in Tab. 12. It is important to emphasize that all two-dimensional viscous simulations were considered laminar, without the introduction of a turbulence model,

although high Reynolds number were employed in the simulations.

Table 11 Computational data of the reactive simulations with the 2D blunt body.

Studied case	CFL	Iterations	Orders of Reduction of the Residual
First-Order/Structured/Inviscid/TECNE ⁽¹⁾	0.9	250	4
First-Order/Structured/Viscous/TECNE	0.7	1,005	4
Second-Order/Structured/Inviscid/TECNE	0.9	346	4
Second-Order/Structured/Viscous/TECNE	0.7	1,194	4
First-Order/Unstructured/Inviscid/TECNE	0.3	1,304	4
First-Order/Unstructured/Viscous/TECNE	0.1	8,069	4
First-Order/Structured/Inviscid/TCNE ⁽²⁾	0.9	373	4
First-Order/Structured/Viscous/TCNE	0.7	1,005	4
Second-Order/Structured/Inviscid/TCNE	0.9	331	4
Second-Order/Structured/Viscous/TCNE	0.7	1,182	4
First-Order/Unstructured/Inviscid/TCNE	0.1	3,348	4
First-Order/Unstructured/Viscous/TCNE	0.1	7,389	4

⁽¹⁾ TECNE: Thermal Equilibrium and Chemical Non-Equilibrium; ⁽²⁾ TCNE: Thermal and Chemical Non-Equilibrium.

Table 12 exhibits the computational costs of the [17] scheme in the two-dimensional reactive formulations. This cost is evaluated in seconds/per iteration/per computational cell. They were calculated using a notebook with 2.13 GHz of “clock” and 1.0 GBytes of RAM, in the Windows Vista Starter environment. In the two-dimensional case, considering thermal equilibrium and chemical non-equilibrium, the cheapest algorithm was due to

[17], inviscid, first-order of accuracy, unstructured, whereas the most expensive was due to [17], viscous, second-order accurate, structured. In relative percentage terms, the former is 70.89% cheaper than the later. Considering, now, thermochemical non-equilibrium, the cheapest algorithm was due to [17], inviscid, first-order of accuracy, unstructured, whereas the most expensive was due to [17], viscous, second-order accurate, structured. In relative percentage terms, the former is 56.56% cheaper than the latter.

Table 12 Computational costs of the [17] scheme in the reactive cases.

Studied case	Computational Cost ⁽¹⁾
First-Order/Structured/Inviscid/TECNE ⁽¹⁾	0.0008065
First-Order/Structured/Viscous/TECNE	0.0011627
Second-Order/Structured/Inviscid/TECNE	0.0009068
Second-Order/Structured/Inviscid/TECNE	0.0012641
First-Order/Unstructured/Inviscid/TECNE	0.0007397
First-Order/Unstructured/Viscous/TECNE	0.0010261
First-Order/Structured/Inviscid/TCNE ⁽²⁾	0.0019639
First-Order/Structured/Viscous/TCNE	0.0028584
Second-Order/Structured/Inviscid/TCNE	0.0021241
Second-Order/Structured/Inviscid/TCNE	0.0030235
First-Order/Unstructured/Inviscid/TCNE	0.0019312
First-Order/Unstructured/Viscous/TCNE	0.0027542

⁽¹⁾ Measured in seconds/per iteration/per computational cell; ⁽²⁾ TECNE: Thermal Equilibrium and Chemical Non-Equilibrium; ⁽³⁾ TCNE: Thermal and Chemical Non-Equilibrium.

The computational costs due to a thermochemical non-equilibrium model are, in general, more

expensive than the thermal equilibrium and chemical non-equilibrium ones. It is due to the most complex development of the thermochemical non-equilibrium theory.

5 Conclusions

This work, the first part of this study, presents a numerical tool implemented to simulate inviscid and viscous flows employing the reactive gas formulation of thermochemical non-equilibrium flow in two-dimensions. The Euler and Navier-Stokes equations, employing a finite volume formulation, on the context of structured and unstructured spatial discretizations, are solved. These variants allow an effective comparison between the two types of spatial discretization aiming verify their potentialities: solution quality, convergence speed, computational cost, etc. The aerospace problem involving the “hot gas” hypersonic flow around a blunt body, in two-dimensions, is simulated.

To the simulations with unstructured spatial discretization, a structured mesh generator developed by the first author ([38]), which creates meshes of quadrilaterals (2D), was employed. After that, as a pre-processing stage ([39]), such meshes were transformed in meshes of triangles. Such procedure aimed to avoid the time which would be waste with the implementation of an unstructured generator, which was not the objective of the present work, and to obtain a generalized algorithm to the solution of the reactive equations.

In this work, first part of this study, the structured formulation of the two-dimensional Euler and Navier-Stokes reactive equations is presented. In [40], the second part of this study, it will be presented the unstructured version of the calculation algorithm in two-dimensions to complete the formulation in structured and in unstructured contexts. However, solutions to the structured and unstructured cases are presented in both papers.

The reactive simulations involved an air chemical model of five species: N, O, N₂, O₂ and NO. Seventeen chemical reactions, involving dissociation and recombination, were simulated by the proposed model. The Arrhenius formula was employed to determine the reaction rates and the law of mass action was used to determine the source terms of each gas specie equation.

The results have demonstrated that the most correct aerodynamic coefficient of lift is obtained by the [17] scheme with second-order accuracy, in an inviscid formulation, to a reactive condition of thermochemical non-equilibrium. Considering

thermochemical non-equilibrium, the cheapest algorithm was due to [17], inviscid, first-order accurate, unstructured. Moreover, the shock position is closer to the geometry as using the reactive formulation than the ideal gas formulation. It was verified in the inviscid and viscous cases. In comparison with the perfect gas formulation, the reactive simulations gave the best results to the [17] scheme in its second order accuracy version, according to the expected behaviour for a high resolution scheme. Errors less than 10% were obtained with this version of the [17] algorithm in the determination of the stagnation pressure at the body nose and less than 6% in the determination of the shock standoff distance, highlighting the correct implementation and good results obtained from the reactive formulation. Values of these parameters were evaluated and proved the significant potential of the present numerical tool.

This work, as also [40], is the continuation of the study started at [41], based on the work of [42]. Other references on the non-equilibrium reactive flows area are: [43], [44] and [45].

6 Acknowledgments

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