

Finally, the solution is given by our solver in the 0.001 second (time of resolution). The value for each variable is: $y_1 = v_1$, $y_2 = v_3$ and $y_3 = v_7$ such that this solution is coded in the following way: $SHOES = Cordovans$, $SHIRT = green$ and $SLACKS = gray$. We show that, the number of violated constraints is 1 because the tuple $(Cordovans, green)$ violate the constraint $C(SHOES, SHIRT)$ (remark 3).

4.2 Numerical results

In order to show the practical interest of the proposed approach, the experiments are achieved to solve some typical problems of different natures. These series represent a large spectrum of instances [22]. These experiments are effectuated in personal computer with a 2.79 GHz processor and 512 MB RAM. The performance has been measured in terms of the CPU time per second.

This solver is modeled by the Unified Modeling Language method and implemented by java language. The starting points are chosen in such a way that the points corresponding to the most constrained variables are the most favored in the processing. This choice allows the continuous Hopfield network to handle in a first order the variables most constrained. This process lead to an assignment of values to variables such that the number of satisfied constraints is maximized. This is guaranteed by a good affectation to the variables most constrained. Therefore, the maximum of constraints in the problem are satisfied. Finally, the starting points are randomly generated by the following expression:

$$x_{ir} = 0.8 + 0.19 \frac{NVC_i}{NVMC} + 10^{-2}U$$

Where NVC_i is the number of participation for each variable y_i in the set of constraints C ,

$NVMC = \max \left\{ NVC_i / i \in \{1, \dots, n\} \right\}$ representing the more present variable in the constraints of the Max-CSP problem, and U is a random variable in the interval $[-0.5, 0.5]$. Recall that n is the number of variables. Based on a series of experiments, α and ε are determined by the following values:

$$\alpha = \frac{1}{n}, \quad \varepsilon = 10^{-4}$$

In this experimentation, some instances as benchmarks for the first round of the 2008 Max-

CSPs [22] solver competition are used to test this algorithm (See Table 1).

A statistical study was represented in order to examine the quality of our approach. This study is based on the computation of performance operators. In fact, the quality of solutions obtained by our approach was evaluated in terms of performance report:

$$\rho = \frac{\text{number of violated constraints obtained by this approach}}{\text{best number of violated constraints obtained by the best solver}}$$

Among these operators performance, we have (Table 1):

- Ratio mode: the ratio between the most repetitive (mode) number of violated constraints (the optimal value obtained by CHN) in the number of run and the least number of violated constraints (best results existing in the literature) obtained by the best solver, Ratio mean: the ratio between the average number of violated constraints in a number of run and the best results existing in the benchmarks obtained by other solver,
- Ratio minimum : the ratio of the smaller number of violated constraints (better results obtained by our solver) and the best result existing in the literature obtained by other solver,
- Mean of CPU time: the average time consumed to obtain the solution in a number of run.

We show that, for each instance, if Ratio minimum is less than 1 then the proposed approach gives the best results than the others, i.e., gives a solution that violates fewer constraints compared to the best existing solver. Also Ratio minimum is superior to 1 then the proposed approach cannot give the results better than the others, i.e., gives a solution that violates more constraints compared to the best existing solver. Moreover, if Ratio minimum is equals to 1, in this case the given results is similar to the best solver existing in benchmarks (Table 1).

In comparison with other Max-CSPs solvers, the time of resolution obtained by our software is better than others; it does not exceed 1 second for the most of instances. Generally, our solver is very successful, it happens to get the solution to the maximal constraint satisfaction problems in a minimum time than the author solvers of Max-CSP [22] (See Table 1). For example, instances “kbtrees-9-7-3-5-90-08”, “cnf-2-40-1800-067529”, “maxcut-30-400-5”, “maxcut-30-340-5”, etc, the proposed solver gives a solution that violates fewer constraints compared to the best existing solver.

Name of instances	number of constraint	Best result obtained on benchmark	Best CPU time obtained on benchmark	Number of run	Ratio Minimum	Ratio mean	Ratio mode	Mean of iterations	mean of CPU Time
geom-40-2	78	22	0.03s	200	1.05	1.36	1.27	58.76	0.006s
geom-30a-4	81	4	0.323 s	200	1.25	3.26	2.75	192.29	0.046s
vcsp-25-10-25-87-44	75	32	5.198s	200	1.38	1.99	1.78	254.42	0.212s
vcsp-25-10-21-85-33	63	19	0.219 s	200	1.58	2.81	2.42	261.8	0.255s
vcsp-25-10-25-87-36	75	29	1.587 s	200	1.21	2.71	1.86	244.96	0.209s
scenw-6-sub4-20	477	23	0.132 s	100	1.83	4.91	2.39	326.1	1.023s
scenw-6-sub2	353	22	0.374s	100	1.32	3.96	1.86	326.31	2.466s
scenw-6-sub2	353	22	0.374s	100	1.32	3.96	1.86	326.31	2.466s
kbtree-9-7-3-5-90-08	189	123	0.311 s	100	0.93	1.44	1.24	235.43	0.076s
kbtree-9-7-3-5-60-01	189	54	0.335s	100	1.17	2.1	1.48	214.25	0.071s
kbtree-9-7-3-5-90-11	189	123	0.338s	100	0.98	1.52	1.24	213.16	0.068s
kbtree-9-7-3-5-80-50	189	97	0.846 s	100	1.03	1.73	1.26	189.65	0.062s
kbtree-9-7-3-5-70-50	189	72	1.522s	100	1.07	1.84	1.46	217.16	0.069s
kbtree-9-5-3-5-90-45	255	163	2.297s	100	0.95	1.6	1.21	232.88	0.133s
kbtree-9-5-3-5-90-10	255	167	3.17s	100	1	1.66	1.26	183.89	0.097s
kbtree-9-5-3-5-80-47	255	129	4.969s	100	1.09	1.74	1.34	226.37	0.121s
kbtree-9-5-3-5-80-08	255	134	5.931s	100	1.13	1.51	1.31	266.14	0.141s
kbtree-9-2-3-5-90-29	309	196	461.111s	100	1.06	1.45	1.2	271.75	0.302s
kbtree-9-2-3-5-80-50	309	153	1143.39s	100	1.11	1.86	1.28	236.32	0.263s
cnf-2-80-300-186945	286	25	1.032s	100	1.04	1.3	1.28	35.83	0.015s
cnf-2-40-1800-067529	667	246	1.367s	50	0.97	1.07	1.06	30.68	0.003s
cnf-2-40-1500-890427	640	210	1.417s	50	1.01	1.1	1.06	28.7	0.002s
cnf-2-40-1600-616123	663	227	1.856s	50	0.98	1.06	1.04	27.5	0.002s
cnf-2-40-2500-147426	685	307	2.139s	50	0.99	1.06	1.05	35.94	0.003s
cnf-2-40-2600-873121	670	297	3.418s	50	0.97	1.09	1.05	42.22	0.004s
cnf-2-40-2400-421728	681	291	3.742s	50	1	1.1	1.06	36.94	0.003s
cnf-2-40-2400-421727	683	284	5.117s	50	1.02	1.12	1.07	41	0.003s
cnf-2-80-800-815450	710	102	163.366s	50	1.23	1.3	1.28	19.72	0.010s
cnf-2-80-800-815444	717	107	391.728s	50	1.13	1.25	1.22	29.26	0.013s
cnf-2-80-1100-992546	946	160	979.48s	50	1.08	1.11	1.11	22.08	0.007s
cnf-2-80-1200-718241	989	176	1261.0s	50	1.05	1.13	1.14	30.28	0.010s
maxcut-30-400-5	400	179	6.597s	100	0.97	1.12	1.06	72.73	0.003s
maxcut-40-480-6	480	193	231.657s	100	1.07	1.2	1.17	37.73	0.005s
maxcut-30-340-5	340	142	3228.99s	100	0.99	1.19	1.12	40.86	0.004s
maxcut-30-370-5	370	160	17.851s	100	1.01	1.22	1.09	48.85	0.002s
maxcut-40-420-5	420	161	20.163s	100	1.06	1.23	1.2	40.17	0.004s
maxcut-40-440-6	440	173	29.374 s	100	1.07	1.24	1.14	42.58	0.004s
maxcut-40-480-8	480	192	136.187 s	100	1.03	1.22	1.17	43.99	0.004s
maxcut-40-540-3	540	225	717.983s	50	1.07	1.17	1.12	44.1	0.004s
maxcut-40-520-1	520	210	272.491s	50	1.07	1.27	1.17	33.84	0.003s
maxcut-40-520-10	520	213	340.681s	50	1.08	1.16	1.14	60.08	0.005s
maxcut-50-580-6	580	219	940.592s	50	1.11	1.29	1.19	34.54	0.004s
maxcut-40-580-1	580	241	161.684s	50	1.05	1.22	1.14	52.26	0.005s
maxcut-50-560-10	560	212	176.564s	50	1.07	1.24	1.21	48.58	0.011s
maxcut-60-580-2	580	207	2121.51s	50	1.15	1.26	1.27	31.54	0.007s
c-fat200-2	16865	176	1.217s	25	1.22	1.22	1.22	366.36	0.963s
c-fat500-2	116111	474	283.354s	25	1.24	1.24	1.25	374.12	4.906s
c-fat500-10	78623	374	1101.83s	25	1.32	1.33	1.33	410.08	5.386s
c-fat500-5	102059	436	1151.8s	25	1.38	1.38	1.38	369.2	4.899s

Table 1: Computational results of the typical Max-CSP instances

However, in some cases as “vcsp-25-10-21-85-33”, “kbtree-9-7-3-5-60-01”, “maxcut-50-580-6”, “c-fat500-10”, etc, our approach violate plus the constraints more than author solvers. Finally, we can conclude that the best results are obtained by this approach.

5. Conclusion

In this paper, we have proposed a new approach for solving binary maximal constraint satisfaction problems. The interesting steps of this approach are: proposing the new model of maximal constraint satisfaction problem as a 0-1 quadratic program subject to linear constraints and using the continuous Hopfield network to solve this problem. The most interesting propriety of this approach is used to give the solution of the binary Max-CSP. It is also interesting to note that this method can be used with a non-binary Max-CSP after converting the latter into a binary Max-CSP [14]. The experimental results show that our method can find a good optimal solution in short time compared to other solvers. Future directions of this research are reducing the architecture of Hopfield neural network and applying this approach to get a good solution of real world problems such as warehouse location problem, max-clique and max-cut.

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