

Design and Simulation Analysis of Interleaved Buck Converter In Network Communication for Femto Technology

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Abstract: - This paper describes about a design and simulation analysis of Interleaved Buck Converter in network communication for Femto Technology. The evolution of wireless broadband technology improves the data speed and coverage and avoids the web surfing of the network which can be done by using Femtocells without the need of the expensive cell towers. They are low power consumption of 12V for 3G, 6V for 4G, 5V for 5G and low-cost user deployed base station able to provide high service in residential, enterprise and metro cells. In the hardware architecture of the femto cell, the DC-DC converter such as Buck converter plays an important role which converts from the higher voltage to lower voltage towards the supply side of the femto cell. In this converter, the switching losses and inductor AC losses are more, efficiency is less, power density and pf are less. In order to overcome from these limitations, interleaved buck converter has been introduced which has low switching losses & improves step down conversion ratio suitable for high input with the duty ratio less than that of 0.5%. A closed loop control is achieved by designing a digital PID controller to achieve the proper regulator for this converter. For the enhancement in updating the technology, this converter is connected to the GPRS IOT for the improvement in the network strength. The design and analysis of the closed loop control of the Interleaved buck converter with the input voltage of 12V and output voltage of 5V with the power rating of 10W for the Femto technology has been discussed. In this proposed paper the hardware architecture of the femto cells along with the design and analysis of the closed loop Interleaved buck converter with the GPRS module has been validated.

Key-Words: - Femtocells, Interleaved Buck Converter, PID controller, GPRS module

1 Introduction

In cellular network communications, the high-speed coverage connection and generation of large traffic data of the network has been consumed by many services like web surfing, video streaming, email downloading, image downloading and video calls. The attenuations of the walls, multiple losses, scattering of the spectrum analysis are the primary problem for the poor cellular network communication [1]. The main challenge of the

operators is to provide the good indoor coverage in cost effective manner with excellent network strength. The invent of the femtocells help to reduce the cell phone traffic which is soon riding on the consumers broadband line [2]. The poor coverage slows down the high-speed data rates and reduces the quality of video and voice applications. The vendors constantly provide with the solution to utilize best among the limited radio resources and improves Quality of Services (QoS) especially in the rural areas. Various solutions like Distributed

Antenna System (DAS), microcell, picocells, has been evolved to overcome from the poor coverage problem [3]. But these cells have a disadvantage of high capital cost, leased backhaul connection, increases the electricity bills etc. Hence all these problems have led to the solution of the cost-effective technology which is a Femtocell [4].

A small box that plugs into the users existing broadband internet connections and works with the existing mobile networks is a Femtocell. These femto cells are fully featured, short range mobile phone base station has been evolved to avoid the existing problems like lack of indoor coverage and low data rates [5]. It is a low power base station with the low power range can be deployed in residence, office and enterprise applications. The main difference between the base station and femtocell is the radius of base station and femtocells are 20-30meter and 10 meters respectively [6]. The plug and play capability of the femtocells helps the user for the easy installation and usage. It provides excellent mobile coverage and data speed at home, office, and public areas for both voice and data. For 3G, 4G or Long-term Evolution these Femto cells has been developed and approaching to NextGen i.e 5G by 2020 for better enhancement and data speed rates with multiple access [6].

There are many four types of small cells namely, the first one is Femtocells which is closed access with the 4 -8 users are operating within the radius of 10m [7]. The second one is metro cells which is hybrid/open access with the 8 -32 users can be operated with the radius range of 200m. The third one is Pico or Micro cells which is an open access with the 32 -more than 100 users [8]. The fourth one is macro cell which is an open access with more than 1000 users. The femtocell can be classified into three cells i.e Home cell, Enterprise cell and Metro cells [9]. It supports 4 users in a residential setting & 4 to 32 users in enterprise cell, 16 users in metro cells [10]. The different types of femtocell is as shown in the figure 1.2(a)(b)(c).

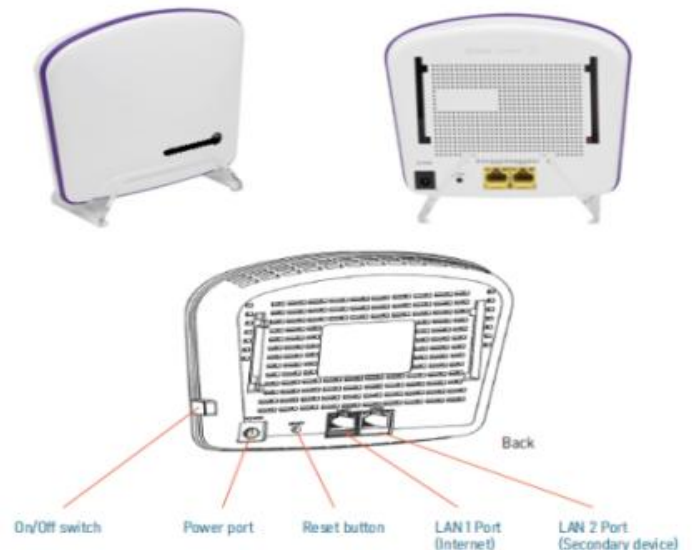


Fig 1.2(a): Front and back view of Femtocell



Fig 1.2(b): Variant of Enterprise Femtocell



Fig 1.2(c): Different types of Metro Femtocell



Fig1.3: Various components of Femtocell

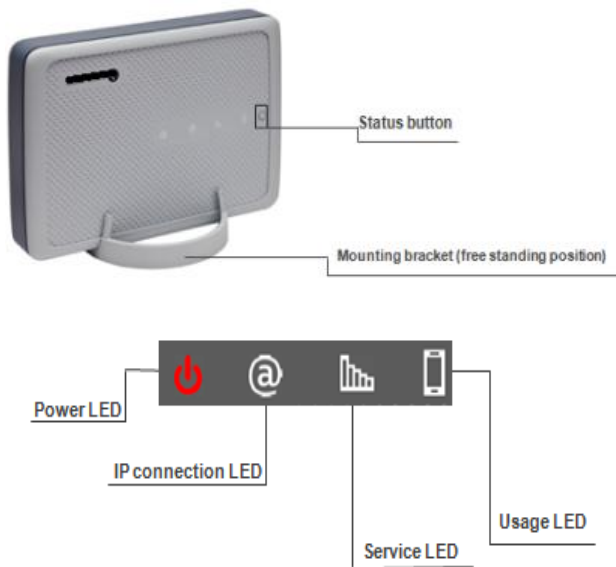


Fig1.4: Significance of LED of Femtocell

2 Hardware Architecture of Femto cell towards supply side

The components present in the hardware architecture of the femtocell are namely, DC -DC converter as Buck converter, PWR switching, Power Over Ethernet (POE) and PMIC chip which manages all the associated elements for the processing of the operations [1]. The block diagram of Femtocell towards supply side is as shown in Fig2.

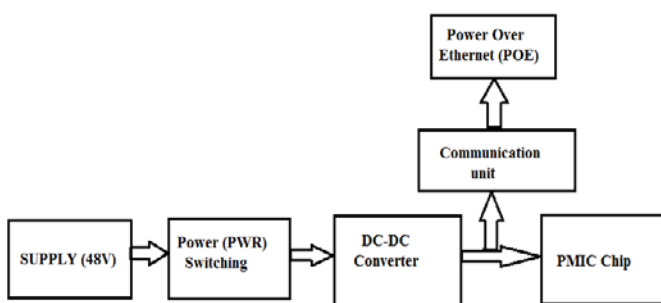


Fig 2: Block Diagram of FEMTO cell towards supply side

2.1 Supply: The primary function of a power supply is to convert electric current from a source of

48V for enterprise cell and 12V for home cell which delivers power to the load [2].

2.2 Power (PWR) Switching: Power switching is a Switch Mode Power Supply (SMPS) is an electronic power supply that incorporates a switching regulator to convert electrical power more efficiently.

2.3 DC-DC Converter: A DC-to-DC converter is an electronic circuit that converts a source of direct current (DC) from one voltage level to another. A buck converter (step-down converter) is a DC-to-DC power converter which steps down voltage from its input (supply) to its output (load). It has a input voltage of 12V converts into the output voltage of 5V efficiently which extends prolonged battery life, reduces heat dissipation.

2.4 Power Over Ethernet (POE): Power over Ethernet or POE is a standard system which pass electric power along with data on twisted pair Ethernet cabling. This allows a single cable to provide both data connection and electric power to devices such as wireless access points like LAN port.

2.5 PMIC: They are integrated circuits for managing power requirements of the system. It is often included in battery-operated devices such as mobile phones and portable media players to decrease the amount of space required. Power management ICs are solid state devices that control the flow and direction of electrical power [5]. It has a ability to perform some basic electrical functions including voltage conversion, voltage scaling, power source selection. It is equally suitable for DC-to-DC conversion on board without losing the bit of accuracy and quality of the signal. It is used for individual power conversion, where more than one function can be employed on the single IC based on the nature and quality of the product they

are going to be installed. These ICs helps in reducing the number of components required to perform number of functions on a single chip [6].

3 Methodology of Interleaved Buck Converter for Femtocell technology

In the supply side of the Femtocell has a buck converter which converts from higher voltage of 12V to a lower voltage to 5V, but this converter has a limitations of higher switching losses and reduces efficiency. In order to overcome from these limitations, the interleaved buck converter are introduced which provides a high efficiency, less output current ripple, simple in structure and operates with high switching frequency. The word 'Interleaving' refers to paralleling which shares the power flow between two or more conversion chain and helps to minimize the input current ripple and increases efficiency on the converter. The block diagram of closed loop of Interleaved buck converter is as shown in the figure 3. It is mainly consisting of following components namely,

3.1 DC supply: The function of the DC supply is to provide 12V DC like battery which gives power for the operation of the converter.

3.2 Design and development of Interleaved converter: This converter shares the power flow between two or more conversion chain which helps to minimize the input current ripple and to achieve high efficiency on the converter. It implies a reduction in the size, weight and volume of the inductors and capacitors. Due to the simple structure and low control complexity of interleaved buck converter, it is used in applications where non-isolation, step down conversion ratio, high output current with low ripple is required [3].

3.3 Design and development of PID Controller: To meet the steady state stability by

minimizing the transients in the initial conditions. It avoids the fluctuations and ripple present in the output voltage. The output voltage of this proposed converter is given to the transmitter of GPRS module.

3.4 Transmitter chip [ESP8266EX]: The function of the transmitter is to transmits the voltage value from one station to another station. It helps to send the information even in the remote station in order to control the requirement.

3.5 Receiver of the GPRS IoT module: It receives the variation of the voltage value even in remote station which can be regulated by using the PID controller

3.6 Server Graph Plot: This is the display unit of the voltage value which is received from the transmitter[8].

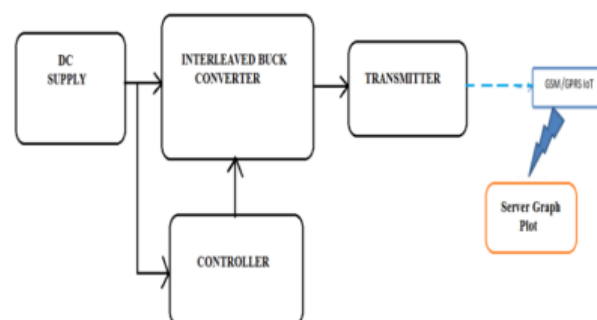


Fig 3: Block diagram of closed loop of Interleaved buck converter for the Femto cell technology

4 Circuit Diagram of Interleaved Buck Converter for Femtocell technology

The Interleaved Buck Converter has low switching losses and improved step-down conversion ratio, which is suitable for the applications where the input voltage is high and the operating duty is below 50%. The voltage stress across all the active switches is half of the input voltage before turn-on or after turn-off when the operating duty is below 50%, the capacitive discharging and switching losses can be reduced. The circuit diagram of interleaved buck converter is as shown in the figure 4.1. It consists of two active switches Q1 & Q2, inductors L1 & L2 , diodes D1 & D2, capacitor C, resistor R load and the voltage source Vin.

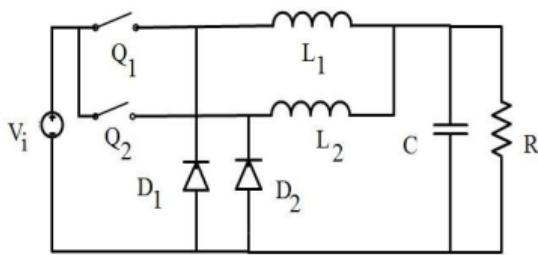


Fig 4.1: Circuit diagram of the Interleaved buck converter

The capacitor C should be large should be large enough in order to maintain the constant output voltage Vo. All the power semiconductors should be ideal in nature. The two inductors L1 & L2 should be same. Coupling capacitor helps to connects the two circuit which allows AC i.e high frequency and blocks DC i.e low frequency should be large which acts as a voltage source. The circuit diagram of interleaved buck converter consists of 4 modes namely

4.1 Mode 1 (t0 – t1): Mode 1 begins when Q1 is turned ON & D2 is Forward biased at to. The current iL1(t) flows through Q1, Cb & L1 and voltage of coupling capacitor Vcb is charged. The voltage across inductor L1 is VL1= Vs-Vcb-Vo (+ve value), hence iL1(t) increases linearly and voltage across inductor L2 is VL2= -Vo(-ve value),hence iL2(t) decreases linearly. The voltage across the switch Q2 and diode D1 are Vq2= Vs & Vd1= Vs- Vcb respectively. The circuit diagram of

the mode 1 operation is shown in the figure 4.2. The equation obtained during the mode 1 operation is as follows

$$V_{L_1}(t) = V_S - V_{CB} - V_O \tag{1}$$

$$V_{L_2}(t) = -V_O \tag{2}$$

$$I_{L_1}(t) = \frac{V_S - V_{CB} - V_O}{L(t - t_0) + I_{L_1}(t_0)} = I_{Q_1}(t) = I_{CB}(t) \tag{3}$$

$$I_{L_2}(t) = \frac{V_O}{L(t - t_0) + I_{L_2}(t_0)} = I_{D_2}(t) \tag{4}$$

$$V_{Q_2} = V_S \tag{5}$$

$$V_{D_1} = V_S - V_{CB} \tag{6}$$

$$V_{CB} = V_{CB}(t_0) + I_0/V_{CB}(t - t_0) \tag{7}$$

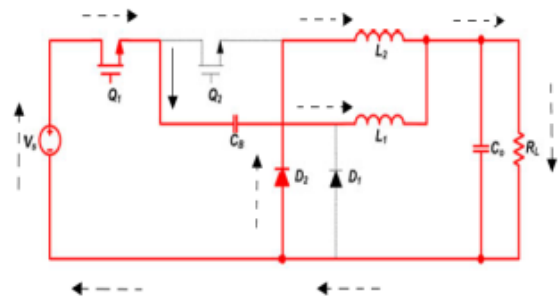


Fig 4.2: Circuit diagram for Mode 1 operation

4.2 Mode 2 (t1 – t2): The Mode 2 begins when Q1 is turned OFF at t1. The currents iL1(t) and iL2(t) freewheels through D1 and D2 respectively. The voltage across inductor L1 and L2 are VL1(t) =VL2(t) = -Vo (-ve value) hence iL1(t) and iL2(t) decreases linearly. The voltage across the switch Q1 and diode Q2 are Vq1(t) = Vs – Vcb and Vq2(t) = Vcb respectively. The circuit diagram of the mode 2 operation is shown in the figure 4.3. he equation obtained during the mode 2 operation is as follows

$$V_{L_1}(t) = V_{L_2}(t) = -V_O \tag{8}$$

$$I_{L_1}(t) = I_{L_1}(t_1) - \left(\frac{V_O}{L}\right)(t - t_1) = I_{D_1}(t) \tag{9}$$

$$I_{L_2}(t) = I_{L_2}(t_1) - \left(\frac{V_O}{L}\right)(t - t_1) = I_{D_2}(t) \tag{10}$$

$$V_{Q_1}(t) = V_S - V_{CB} \tag{11}$$

$$V_{Q_2}(t) = V_{CB} \tag{12}$$

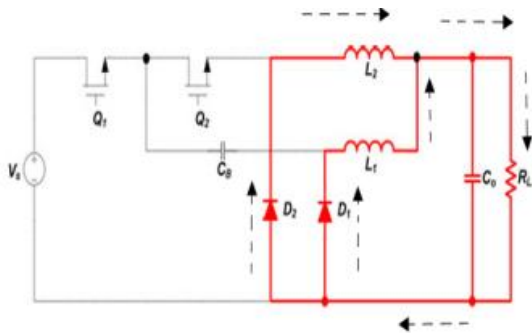


Fig 4.3: Circuit diagram for Mode 2 operation

4.3 Mode 3 (t2 – t3): The Mode 3 begins when Q2 is turned ON at t2. The current iL1(t) freewheels through D1 and iL2(t) flows through D1, Cb, Q2 & L2. Thus Vcb is discharged. The voltage across inductor L1 is VL1= -Vo (-ve value), hence iL1(t) decreases linearly. The voltage across inductor L2 is VL2=Vcb-Vo(+ve value),hence iL2(t) increases linearly. The voltage across the switch Q1 and diode D1 are Vq1= Vs - Vcb & Vd1= Vcb respectively. The circuit diagram of the mode 3 operation is shown in the figure 4.4. The equation obtained during the mode 3 operation is as follows

$$\begin{aligned}
 V_{L1}(t) &= -V_o & (13) \\
 V_{L2}(t) &= V_{CB} - V_o & (14) \\
 I_{L1}(t) &= \left(\frac{-V_o}{L}\right)(t - t_1) + I_{L1}(t_2) & (15) \\
 I_{L2}(t) &= \left(\frac{(V_{CB} - V_o)}{L}\right)(t - t_2) + I_{L2}(t_2) & (16) \\
 I_{D1}(t) &= I_{Q2}(t) = -I_{CB}(t) & (17) \\
 I_{D1}(t) &= I_{L1}(t) + I_{L2}(t) & (18) \\
 V_{Q1} &= V_s - V_{CB} & (19) \\
 V_{D2} &= V_{CB} & (19)
 \end{aligned}$$

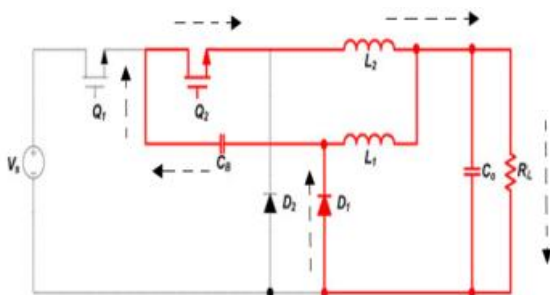


Fig 4.4: Circuit diagram for Mode 3 operation

4.4 Mode 4 (t3 – t4): Mode 4 begins when Q2 is turned OFF at t3, and its operation is same as Mode

2. The gate pulses given for the interleaved buck converter is shown in the figure 4.5

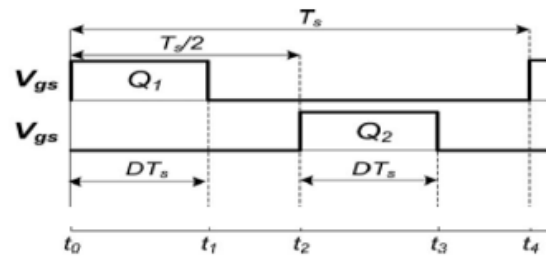


Fig 4.5: Gate pulses given for Interleaved Buck Converter

According to the design the inductor value is given by the equation $L = [(Vs-Vo)/diL * 2f]^2 * D$ and $L1 = L2 = L/2$. The capacitor value is given by the equation $C = (1-2D)/ 8 * L * (dV/Vo) * (2 * f)^2$. The components value present in the circuit diagram is shown in the table 1

Table 1: Specification the components value according to the design

Sl.no	Name of the parameter	Values
1.	Input Voltage	12V
2.	Output Voltage	5V
3.	Power Rating	10W
4.	Inductor L1 & L2	1.439mH
5.	Capacitor	21.71nF
6.	Switching frequency	100KHz
7.	Resistance	10ohm

5 Simulation results of the Interleaved Buck Converter

5.1 Open loop simulation

The simulation circuit and result of the interleaved buck converter in open loop is as shown in figure 5.1 (a) (b) (c)

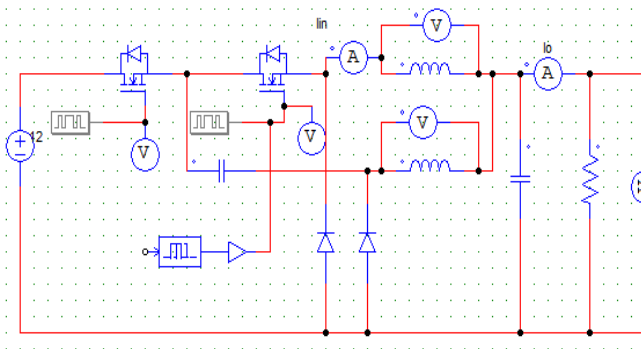


Fig 5.1 (a): Open Loop Simulation of the interleaved buck converter

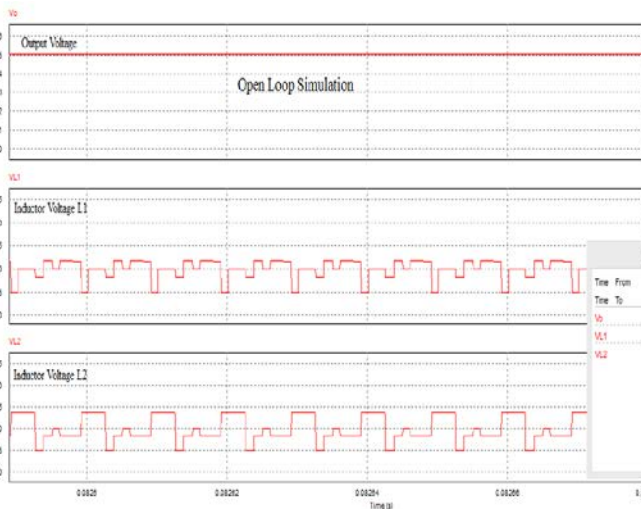


Fig 5.1 (b): Open Loop Simulation result of V_o , V_{L1} & V_{L2} voltages of interleaved buck converter

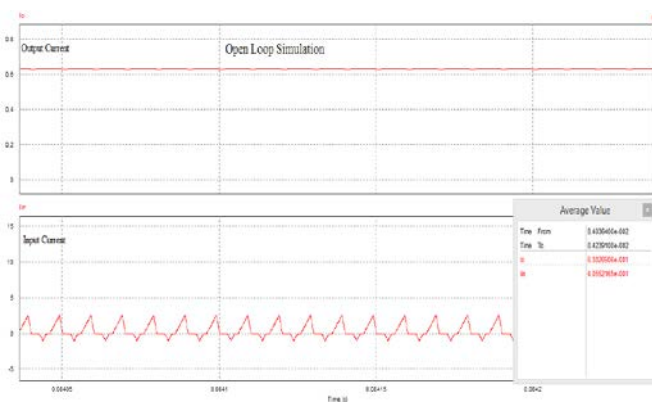


Fig 5.1(c): Open Loop Simulation result of I_o , I_{in} current of interleaved buck converter

5.2 Closed loop simulation

The simulation circuit and result of the interleaved buck converter in closed loop is as shown in figure 5.2 (a) (b) (c)

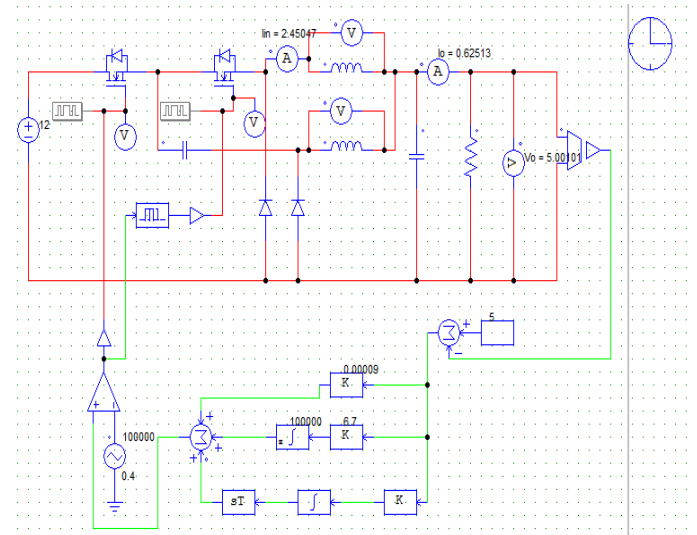


Fig 5.2(a): Closed Loop Simulation of the interleaved buck converter with PID controller

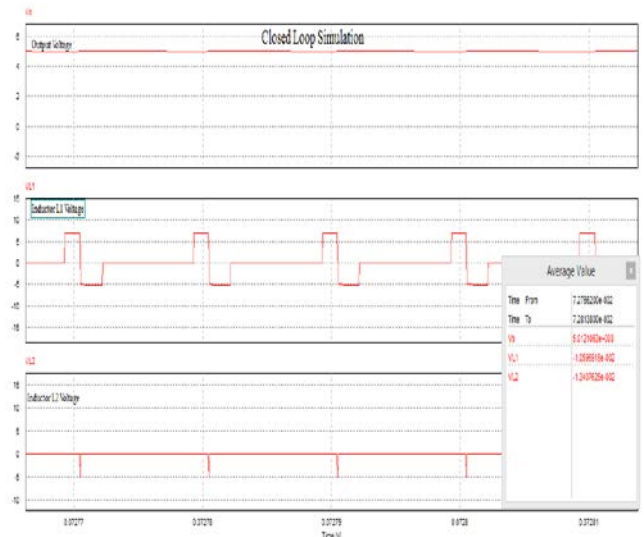


Fig 5.2(b): Closed Loop Simulation result of V_o , V_{L1} & V_{L2} voltages of interleaved buck converter

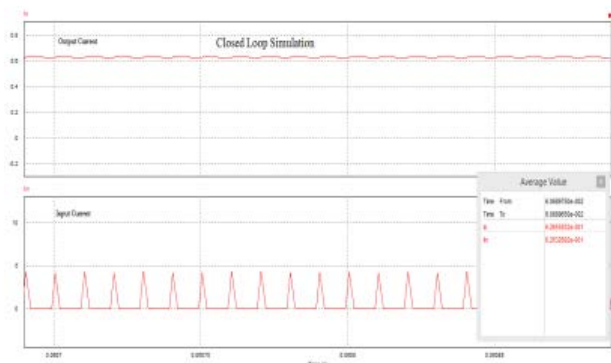


Fig 5.2(c): Closed Loop Simulation result of I_o , I_{in} current of interleaved buck converter

6 Results and Discussion

The overall outcome of the interleaved buck converter for Femto cell is outlined as follows:

Table 2: Open Loop simulation results of Interleaved Buck converter for femtocell technology

Sl.no	Name of the Parameters	Result values
1	Input Voltage V_{in}	12V
2	Output Voltage V_o	5.04V
3	Input Current I_{in}	0.63A
4	Output Current I_o	0.405A
5	Output voltage ripple	3.2%
6	Output current ripple	0.4%
7	Voltage from Inductor L1	0.0389V
8	Voltage from Inductor L2	0.0230V
9	Current from Inductor L1	0.3832A
10	Current from Inductor L2	0.25A

Table 3: Closed Loop simulation results of Interleaved Buck converter for femtocell technology

Sl.no	Name of the Parameters	Result values
1	Input Voltage V_{in}	12V
2	Output Voltage V_o	5.012V
3	Input Current I_{in}	0.62655A
4	Output Current I_o	0.62632A
5	Output voltage ripple	2.5%
6	Output current ripple	0.2%
7	Voltage from Inductor L1	0.01059V
8	Voltage from Inductor L2	0.0134V
9	Current from Inductor L1	0.6249A
10	Current from Inductor L2	0.0000149A

1. In order to maintain output voltage constant With respect to fluctuation in the input, PID controller has been used.

2. Output voltage and output current ripples are less in closed loop simulation when compared to open loop.

3. The efficiency of this converter for femtocell technology in open loop is 40% but in the closed the efficiency has increased up to 60%.

4. Interleaved refers to paralleling of the two circuits which reduces the input ripples of the voltage and current compared to conventional buck converter.

6 Conclusion

In this paper, the different types of small cells used for strengthening the network connectivity along with the femtocell technology has been discussed. In order to reduce the input voltage ripple and to increase the efficiency interleaved buck converter is

suitable for the supply side of the femtocell. The role of power electronics on the supply side of the femtocells are discussed. In the block diagram of the closed loop of PID controller, the importance of the transmitter and receiver has been analyzed. Hence the comparison of the open loop and the closed operation of the interleaved buck converter has been done with the increasing in the stability along with dynamic performance by using PID controller has been achieved with the simulation results.

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