# Positive periodic solutions for an impulsive neutral delay model of single-species population growth on time scales 

MENG HU<br>Anyang Normal University<br>School of mathematics and statistics<br>Xuangedadao Road 436, 455000 Anyang CHINA<br>humeng2001@126.com

LILI WANG<br>Anyang Normal University<br>School of mathematics and statistics<br>Xuangedadao Road 436, 455000 Anyang<br>CHINA<br>ay_wanglili@126.com


#### Abstract

By using a fixed point theorem of strict-set-contraction, some criteria are established for the existence of positive periodic solutions for an impulsive neutral delay model of single-species population growth on time scales. Finally, an example is given to illustrate the main results.


Key-Words: Positive periodic solution; Neutral delay model; Impulse; Strict-set-contraction; Time scale.

## 1 Introduction

In 1993, Kuang [1] proposed an open problem (Open problem 9.2) to obtain sufficient conditions for the existence of positive periodic solutions to

$$
\begin{align*}
x^{\prime}(t)= & x(t)[a(t)-\beta(t) x(t)-b(t) x(t-\tau(t)) \\
& \left.-c(t) x^{\prime}(t-\tau(t))\right], \tag{1}
\end{align*}
$$

where $a, \beta, b, c, \tau$ are nonnegative continuous periodic functions. Since then, different classes of neutral functional differential equations have been extensively studied, we refer the readers to $[1-5]$ and the references therein.

However, in the natural world, there are many species whose developing processes are both continuous and discrete. Hence, using the only differential equation or difference equation can't accurately describe the law of their developments. Therefore, there is a need to establish correspondent dynamic models on new time scales.

The theory of calculus on time scales (see [6] and references cited therein) was initiated by Stefan Hilger [7] in order to unify continuous and discrete analysis, and it has a tremendous potential for applications and has recently received much attention since his foundational work (see, e.g., 8-14). Therefore, it is practicable to study that on time scales which can unify the continuous and discrete situations.

Motivated by above, the aim of this paper is to establish sufficient conditions for the existence of positive periodic solutions for a neutral delay model of single-species population growth on time scales. However, it is known that many real world phenomena often behave in a piecewise continuous frame inter-
laced with abrupt changes. Thus, the choice of system accompanied with impulsive conditions is much more appropriate.

Consider the following impulsive neutral delay model of single-species population growth on time scales

$$
\left\{\begin{align*}
x^{\Delta}(t)= & x(t)[r(t)-a(t) x(t)  \tag{2}\\
& -\sum_{j=1}^{n} a_{j}(t) x\left(t-\tau_{j}(t)\right) \\
& -\sum_{j=1}^{n} b_{j}(t) \int_{-T_{j}}^{0} K_{j}(s) x(t+s) \Delta s \\
& \left.-\sum_{j=1}^{n} c_{j}(t) x^{\Delta}\left(t-\sigma_{j}(t)\right)\right] \\
& t \neq t_{k}, t \in \mathbb{T} \\
x\left(t_{k}^{+}\right)= & x\left(t_{k}^{-}\right)+I_{k}\left(x\left(t_{k}\right)\right), k=1,2, \cdots,
\end{align*}\right.
$$

where $\mathbb{T}$ is an $\omega$-periodic time scale, and for each interval $\mathbb{I}$ of $\mathbb{R}$, we denote by $\mathbb{I}_{\mathbb{T}}=\mathbb{I} \cap \mathbb{T}$. $r, a, a_{j}, b_{j}, c_{j}$ $\in C\left(\mathbb{T}, \mathbb{R}^{+}\right)(j=1,2, \ldots, n)$ are $\omega$-periodic functions, $T_{j} \in(0, \infty)_{\mathbb{T}}, K_{j} \in C\left(\left[-T_{j}, 0\right]_{\mathbb{T}},(0, \infty)\right)$, $\int_{-T_{j}}^{0} K_{j}(s) \Delta s=1(j=1,2, \ldots, n)$ and $\tau_{j}, \sigma_{j} \in$ $C(\mathbb{T}, \mathbb{T})(j=1,2, \ldots, n)$ are $\omega$-periodic functions with respect to their first arguments, respectively. $x\left(t_{k}^{+}\right)$and $x\left(t_{k}^{-}\right)$represent the right and the left limit of $x\left(t_{k}\right)$ in the sense of time scales, in addition, if $t_{k}$ is right-scattered, then $x\left(t_{k}^{+}\right)=x\left(t_{k}\right)$, whereas, if $t_{k}$ is left-scattered, then $x\left(t_{k}^{-}\right)=x\left(t_{k}\right) ; I_{k} \in C\left(\mathbb{R}^{+}, \mathbb{R}^{+}\right)$, $k \in \mathbb{Z}$. There exists a positive constant $p$ such that $t_{k+p}=t_{k}+\omega, I_{k+p}=I_{k}, k \in \mathbb{Z},[0, \omega)_{\mathbb{T}} \cap\left\{t_{k}, k \in\right.$ $\mathbb{Z}\}=\left\{t_{1}, t_{2}, \cdots, t_{p}\right\}$. For the ecological justification of (2), one can refer to [2-4].

## 2 Preliminaries

A time scale $\mathbb{T}$ is a nonempty closed subset of $\mathbb{R}$. The basic theories of calculus on time scales, one can see [6].

Definition 1. ([15]) A time scale $\mathbb{T}$ is periodic if there exists $p>0$ such that if $t \in \mathbb{T}$, then $t \pm p \in \mathbb{T}$. For $\mathbb{T} \neq \mathbb{R}$, the smallest positive $p$ is called the period of the time scale.

Definition 2. ([15]) Let $\mathbb{T} \neq \mathbb{R}$ be a periodic time scale with period $p$. A function $f: \mathbb{T} \rightarrow \mathbb{R}$ is periodic with period $\omega$ if there exists a natural number $n$ such that $\omega=n p, f(t+\omega)=f(t)$ for all $t \in \mathbb{T}$ and $\omega$ is the smallest number such that $f(t+\omega)=f(t)$.

If $\mathbb{T}=\mathbb{R}, f$ is $\omega$-periodic if $\omega$ is the smallest positive number such that $f(t+\omega)=f(t)$ for all $t \in \mathbb{T}$.
Lemma 3. ([6]) If $p$ be a regressive function on $\mathbb{T}$, then
(i) $e_{0}(t, s) \equiv 1$ and $e_{p}(t, t) \equiv 1$;
(ii) $e_{p}(\sigma(t), s)=(I+\mu(t) p(t)) e_{p}(t, s)$;
(iii) $e_{p}(t, s)=e_{p}^{-1}(s, t)$;
(iv) $e_{p}(t, s) e_{p}(s, r)=e_{p}(t, r)$.

Lemma 4. ([6]) Let $r: \mathbb{T} \rightarrow \mathbb{R}$ be right-dense continuous and regressive. The unique solution of the initial value problem

$$
y^{\Delta}=r(t) y+f(t), \quad y\left(t_{0}\right)=y_{0}
$$

is given by

$$
y(t)=e_{r}\left(t, t_{0}\right) y_{0}+\int_{t_{0}}^{t} e_{r}(t, \sigma(\tau)) f(\tau) \Delta \tau
$$

Lemma 5. The function $x(t)$ is an $\omega$-periodic solution of (2), if and only if $x(t)$ is an $\omega$-periodic solution of

$$
\begin{align*}
x(t)= & \int_{t}^{t+\omega} G(t, s) x(s)[a(s) x(s) \\
& +\sum_{j=1}^{n} a_{j}(s) x\left(s-\tau_{j}(s)\right) \\
& +\sum_{j=1}^{n} b_{j}(s) \int_{-T_{j}}^{0} K_{j}(\theta) x(\theta+s) \Delta \theta  \tag{3}\\
& \left.+\sum_{j=1}^{n} c_{j}(s) x^{\Delta}\left(s-\sigma_{j}(s)\right)\right] \Delta s \\
& +\sum_{k: t_{k} \in[t, t+\omega)_{\mathbb{T}}} G\left(t, t_{k}\right) e_{r}\left(\sigma\left(t_{k}\right), t_{k}\right) I_{k}\left(x\left(t_{k}\right)\right)
\end{align*}
$$

where

$$
\begin{equation*}
G(t, s)=\frac{e_{r}(t, \sigma(s))}{1-e_{r}(0, \omega)} \tag{4}
\end{equation*}
$$

Proof: If $x(t)$ is an $\omega$-periodic solution of (2). For any $t \in \mathbb{T}$, there exists $k \in \mathbb{Z}$ such that $t_{k}$ is the first impulsive point after $t$. By using Lemma 4, for $s \in$ $\left[t, t_{k}\right]_{\mathbb{T}}$, we have

$$
\begin{aligned}
x(s)= & e_{r}(s, t) x(t)-\int_{t}^{s} e_{r}(s, \sigma(u)) x(u) \\
& \times\left[a(u) x(u)+\sum_{j=1}^{n} a_{j}(u) x\left(u-\tau_{j}(u)\right)\right. \\
& +\sum_{j=1}^{n} b_{j}(u) \int_{-T_{j}}^{0} K_{j}(\theta) x(\theta+u) \Delta \theta \\
& \left.+\sum_{j=1}^{n} c_{j}(u) x^{\Delta}\left(u-\sigma_{j}(u)\right)\right] \Delta u
\end{aligned}
$$

then

$$
\begin{align*}
x\left(t_{k}\right)= & e_{r}\left(t_{k}, t\right) x(t)-\int_{t}^{t_{k}} e_{r}\left(t_{k}, \sigma(u)\right) x(u) \\
& \times\left[a(u) x(u)+\sum_{j=1}^{n} a_{j}(u) x\left(u-\tau_{j}(u)\right)\right. \\
& +\sum_{j=1}^{n} b_{j}(u) \int_{-T_{j}}^{0} K_{j}(\theta) x(\theta+u) \Delta \theta \\
& \left.+\sum_{j=1}^{n} c_{j}(u) x^{\Delta}\left(u-\sigma_{j}(u)\right)\right] \Delta u \tag{5}
\end{align*}
$$

Again using Lemma 4 and the equality (5), for $s \in$ $\left(t_{k}, t_{k+1}\right]_{\mathbb{T}}$, then

$$
\begin{aligned}
x(s)= & e_{r}\left(s, t_{k}\right) x\left(t_{k}^{+}\right)-\int_{t_{k}}^{s} e_{r}(s, \sigma(u)) x(u) \\
& \times\left[a(u) x(u)+\sum_{j=1}^{n} a_{j}(u) x\left(u-\tau_{j}(u)\right)\right. \\
& +\sum_{j=1}^{n} b_{j}(u) \int_{-T_{j}}^{0} K_{j}(\theta) x(\theta+u) \Delta \theta \\
& \left.+\sum_{j=1}^{n} c_{j}(u) x^{\Delta}\left(u-\sigma_{j}(u)\right)\right] \Delta u \\
= & e_{r}\left(s, t_{k}\right) x\left(t_{k}\right)-\int_{t_{k}}^{s} e_{r}(s, \sigma(u)) x(u) \\
& \times\left[a(u) x(u)+\sum_{j=1}^{n} a_{j}(u) x\left(u-\tau_{j}(u)\right)\right. \\
& +\sum_{j=1}^{n} b_{j}(u) \int_{-T_{j}}^{0} K_{j}(\theta) x(\theta+u) \Delta \theta \\
& \left.+\sum_{j=1}^{n} c_{j}(u) x^{\Delta}\left(u-\sigma_{j}(u)\right)\right] \Delta u
\end{aligned}
$$

$$
\begin{aligned}
& +e_{r}\left(s, t_{k}\right) I_{k}\left(x\left(t_{k}\right)\right) \\
= & e_{r}(s, t) x(t)-\int_{t}^{s} e_{r}(s, \sigma(u)) x(u) \\
& \times\left[a(u) x(u)+\sum_{j=1}^{n} a_{j}(u) x\left(u-\tau_{j}(u)\right)\right. \\
& +\sum_{j=1}^{n} b_{j}(u) \int_{-T_{j}}^{0} K_{j}(\theta) x(\theta+u) \Delta \theta \\
& \left.+\sum_{j=1}^{n} c_{j}(u) x^{\Delta}\left(u-\sigma_{j}(u)\right)\right] \Delta u \\
& +e_{r}\left(s, t_{k}\right) I_{k}\left(x\left(t_{k}\right)\right)
\end{aligned}
$$

Repeating the above process for $s \in[t, t+\omega]_{\mathbb{T}}$, we have

$$
\begin{aligned}
x(s)= & e_{r}(s, t) x(t)-\int_{t}^{s} e_{r}(s, \sigma(u)) x(u) \\
& \times\left[a(u) x(u)+\sum_{j=1}^{n} a_{j}(u) x\left(u-\tau_{j}(u)\right)\right. \\
& +\sum_{j=1}^{n} b_{j}(u) \int_{-T_{j}}^{0} K_{j}(\theta) x(\theta+u) \Delta \theta \\
& \left.+\sum_{j=1}^{n} c_{j}(u) x^{\Delta}\left(u-\sigma_{j}(u)\right)\right] \Delta u \\
& +\sum_{k: t_{k} \in[t, s)_{\mathbb{T}}} e_{r}\left(s, t_{k}\right) I_{k}\left(x\left(t_{k}\right)\right) .
\end{aligned}
$$

Let $s=t+\omega$ in the above equality, we have

$$
\begin{aligned}
x(t+\omega)= & e_{r}(t+\omega, t) x(t) \\
& -\int_{t}^{t+\omega} e_{r}(t+\omega, \sigma(u)) x(u) \\
& \times\left[a(u) x(u)+\sum_{j=1}^{n} a_{j}(u) x\left(u-\tau_{j}(u)\right)\right. \\
& +\sum_{j=1}^{n} b_{j}(u) \int_{-T_{j}}^{0} K_{j}(\theta) x(\theta+u) \Delta \theta \\
& \left.+\sum_{j=1}^{n} c_{j}(u) x^{\Delta}\left(u-\sigma_{j}(u)\right)\right] \Delta u \\
& +\sum_{k: t_{k} \in[t, t+\omega)_{\mathbb{T}}} e_{r}\left(t+\omega, t_{k}\right) I_{k}\left(x\left(t_{k}\right)\right) .
\end{aligned}
$$

Noticing that $x(t+\omega)=x(t)$ and $e_{r}(t, t+\omega)=$ $e_{r}(0, \omega)$, we find that $x(t)$ satisfies (3).

Let $x(t)$ be an $\omega$-periodic solution of (3). If $t \neq$
$t_{i}, i \in \mathbb{Z}$, from (3) we get

$$
\begin{aligned}
& x^{\Delta}(t) \\
& =G(\sigma(t), t+\omega) x(t+\omega)[a(t+\omega) x(t+\omega) \\
& +\sum_{j=1}^{n} a_{j}(t+\omega) x\left(t+\omega-\tau_{j}(t+\omega)\right) \\
& +\sum_{j=1}^{n} b_{j}(t+\omega) \int_{-T_{j}}^{0} K_{j}(\theta) x(\theta+t+\omega) \Delta \theta \\
& \left.+\sum_{j=1}^{n} c_{j}(t+\omega) x^{\Delta}\left(t+\omega-\sigma_{j}(t+\omega)\right)\right] \\
& -G(\sigma(t), t) x(t)[a(t) x(t) \\
& +\sum_{j=1}^{n} a_{j}(t) x\left(t-\tau_{j}(t)\right) \\
& +\sum_{j=1}^{n} b_{j}(t) \int_{-T_{j}}^{0} K_{j}(\theta) x(\theta+t) \Delta \theta \\
& \left.+\sum_{j=1}^{n} c_{j}(t) x^{\Delta}\left(t-\sigma_{j}(t)\right)\right]+r(t) x(t) \\
& =r(t) x(t)-x(t)[a(t) x(t) \\
& +\sum_{j=1}^{n} a_{j}(t) x\left(t-\tau_{j}(t)\right) \\
& +\sum_{j=1}^{n} b_{j}(t) \int_{-T_{j}}^{0} K_{j}(\theta) x(\theta+t) \Delta \theta \\
& \left.+\sum_{j=1}^{n} c_{j}(t) x^{\Delta}\left(t-\sigma_{j}(t)\right)\right] .
\end{aligned}
$$

If $t=t_{i}, i \in \mathbb{Z}$, then by (3) we have

$$
\begin{aligned}
& x\left(t_{i}^{+}\right)-x\left(t_{i}^{-}\right) \\
& \sum_{k: t_{k} \in\left[t_{i}^{+}, t_{i}^{+}+\omega\right)_{\mathbb{T}}} G\left(t_{i}, t_{k}\right) e_{r}\left(\sigma\left(t_{k}\right), t_{k}\right) I_{k}\left(x\left(t_{k}\right)\right) \\
& -\sum_{k: t_{k} \in\left[t_{i}^{-}, t_{i}^{-}+\omega\right)_{\mathbb{T}}} G\left(t_{i}, t_{k}\right) e_{r}\left(\sigma\left(t_{k}\right), t_{k}\right) I_{k}\left(x\left(t_{k}\right)\right) \\
= & G\left(t_{i}, t_{i}+\omega\right) e_{r}\left(\sigma\left(t_{i}+\omega\right), t_{i}+\omega\right) I_{i}\left(x\left(t_{i}+\omega\right)\right) \\
& -G\left(t_{i}, t_{i}\right) e_{r}\left(\sigma\left(t_{i}\right), t_{i}\right) I_{i}\left(x\left(t_{i}\right)\right) \\
= & I_{i}\left(x\left(t_{i}\right)\right)
\end{aligned}
$$

So, $x(t)$ is also an $\omega$-periodic solution of (2). This completes the proof.

In order to obtain the existence of a periodic solution of system (2), we first make the following preparations:

Let $E$ be a Banach space and $K$ be a cone in $E$. The semi-order induced by the cone $K$ is denoted by " $\leq$ ", that is, $x \leq y$ if and only if $y-x \in K$. In addition, for a bounded subset $A \subset E$, let $\alpha_{E}(A)$ denote the (Kuratowski) measure of non-compactness defined by

$$
\begin{array}{r}
\alpha_{E}(A)=\inf \{\delta>0: \text { there is a finite number of } \\
\text { subsets } A_{i} \subset A \text { such that } A=\bigcup_{i} A_{i},
\end{array}
$$

$$
\left.\operatorname{diam}\left(A_{i}\right) \leq \delta\right\}
$$

where $\operatorname{diam}\left(A_{i}\right)$ denotes the diameter of the set $A_{i}$.
Let $E, F$ be two Banach spaces and $D \subset E$, a continuous and bounded map $\Phi: \bar{\Omega} \rightarrow F$ is called $k$-set contractive if for any bounded set $S \subset D$ we have

$$
\alpha_{F}(\Phi(S)) \leq k \alpha_{E}(S)
$$

$\Phi$ is called strict-set-contractive if it is $k$-setcontractive for some $0 \leq k<1$.

The following lemma comes from [16] which is useful for the proof of our main results.

Lemma 6. ([16]) Let $K$ be a cone of the real $B a$ nach space $X$ and $K_{r, R}=\{x \in K \mid r \leq x \leq R\}$ with $R>r>0$. Suppose that $\Phi: K_{r, R} \rightarrow K$ is strict-set-contractive such that one of the following $t$ wo conditions is satisfied:
(i) $\Phi x \not \leq x, \forall x \in K,\|x\|=r$ and $\Phi x \nsupseteq x, \forall x \in$ $K,\|x\|=R$.
(ii) $\Phi x \nsupseteq x, \forall x \in K,\|x\|=r$ and $\Phi x \not \leq x, \forall x \in$ $K,\|x\|=R$.

Then $\Phi$ has at least one fixed point in $K_{r, R}$.
In order to apply Lemma 6 to system (2), we set

$$
C_{\omega}^{0}=\left\{x: x \in C^{0}(\mathbb{T}, \mathbb{R}), x(t+\omega)=x(t)\right\}
$$

with the norm defined by $|x|_{0}=\max _{t \in[0, \omega]_{\mathbb{T}}}\{|x(t)|\}$, and

$$
C_{\omega}^{1}=\left\{x: x \in C^{1}(\mathbb{T}, \mathbb{R}), x(t+\omega)=x(t)\right\}
$$

with the norm defined by $|x|_{1}=\max \left\{|x|_{0},\left|x^{\Delta}\right|_{0}\right\}$. Then $C_{\omega}^{0}$ and $C_{\omega}^{1}$ are all Banach spaces.

Since $\mathbb{T}$ is $\omega$-periodic, $\mu(t)$ is an $\omega$-periodic function, then $\sigma(t+\omega)=\sigma(t)+\omega$. From (4), it is easy to see that $G(t+\omega, s+\omega)=G(t, s)$ and
$A_{0}=\frac{\Upsilon}{1-\Upsilon} \leq G(t, s) \leq \frac{1}{1-\Upsilon}=B_{0}, s \in[t, t+\omega]_{\mathbb{T}}$,
where $\Upsilon=e_{r}(0, \omega)<1$.

For convenience, we introduce the following notations

$$
\begin{aligned}
A_{1}= & \min _{t, t_{k} \in[0, \omega]_{\mathbb{T}}}\left\{G\left(t, t_{k}\right) e_{r}\left(\sigma\left(t_{k}\right), t_{k}\right)\right\} \\
B_{1}= & \max _{t, t_{k} \in[0, \omega]_{\mathbb{T}}}\left\{G\left(t, t_{k}\right) e_{r}\left(\sigma\left(t_{k}\right), t_{k}\right)\right\}, \\
A= & \min \left\{A_{0}, A_{1}\right\}, B=\max \left\{B_{0}, B_{1}\right\} \\
\Theta= & \frac{A}{B}(0<\Theta<1), \\
\Gamma= & \int_{0}^{\omega}\left[\Theta a(s)+\sum_{j=1}^{n} \Theta a_{j}(s)\right. \\
& \left.+\sum_{j=1}^{n} \Theta b_{j}(s)-\sum_{j=1}^{n} c_{j}(s)\right] \Delta s, \\
\Pi= & \int_{0}^{\omega}\left[a(s)+\sum_{j=1}^{n} a_{j}(s)+\sum_{j=1}^{n} b_{j}(s)\right. \\
& \left.+\sum_{j=1}^{n} c_{j}(s)\right] \Delta s, \\
f^{M}= & \max _{t \in[0, \omega]_{\mathbb{T}}}\{f(t)\}, f^{m}=\min _{t \in[0, \omega]_{\mathbb{T}}}\{f(t)\},
\end{aligned}
$$

where $f$ is a continuous $\omega$-periodic function. Throughout this paper, we assume that
$\left(H_{1}\right) \Theta a(t)+\sum_{j=1}^{n} \Theta a_{j}(t)+\sum_{j=1}^{n} \Theta b_{j}(t)$ $-\sum_{j=1}^{n} c_{j}(t) \geq 0$.
$\left(H_{2}\right)\left(1+r^{m}\right) A_{0} \Theta \Gamma \geq \max _{t \in[0, \omega]_{\mathbb{T}}}\left\{a(t)+\sum_{j=1}^{n} a_{i j}(t)\right.$ $\left.+\sum_{j=1}^{n} b_{i j}(t)+\sum_{j=1}^{n} c_{i j}(t)\right\}$.
$\left(H_{3}\right) \frac{\Pi\left(r^{M}-1\right) B_{0}}{\Theta} \leq \min _{t \in[0, \omega]_{\mathbb{T}}}\left\{\Theta a(t)+\sum_{j=1}^{n} \Theta a_{i j}(t)\right.$ $\left.+\sum_{j=1}^{n} \Theta b_{i j}(t)-\sum_{j=1}^{n} c_{i j}(t)\right\}$.
$\left(H_{4}\right) \max \left\{\sum_{k=1}^{p} I_{k}(v)\right\} \leq M|v|_{0}$, where $M>0$ is a sufficient large number.

Define the cone $K$ in $C_{\omega}^{1}$ by

$$
\begin{equation*}
K=\left\{x: \in C_{\omega}^{1}, x(t) \geq \Theta|x|_{1}, t \in[0, \omega]_{\mathbb{T}}\right\} \tag{6}
\end{equation*}
$$

Let $\Phi$ be a map defined by

$$
\begin{align*}
(\Phi x)(t)= & \int_{t}^{t+\omega} G(t, s) x(s)[a(s) x(s) \\
& +\sum_{j=1}^{n} a_{j}(s) x\left(s-\tau_{j}(s)\right)  \tag{7}\\
& +\sum_{j=1}^{n} b_{j}(s) \int_{-T_{j}}^{0} K_{j}(\theta) x(\theta+s) \Delta \theta \\
& \left.+\sum_{j=1}^{n} c_{j}(s) x^{\Delta}\left(s-\sigma_{j}(s)\right)\right] \Delta s \\
+ & \sum_{k: t_{k} \in[t, t+\omega)_{\mathbb{T}}} G\left(t, t_{k}\right) e_{r}\left(\sigma\left(t_{k}\right), t_{k}\right) I_{k}\left(x\left(t_{k}\right)\right)
\end{align*}
$$

where $x \in K, t \in \mathbb{R}$, and $G(t, s)$ is given by (4).
In the following, we will give some lemmas concerning $K$ and $\Phi$ defined by (6) and (7), respectively.
Lemma 7. Assume that $\left(H_{1}\right)-\left(H_{2}\right)$ hold.
(i) If $r^{M} \leq 1$, then $\Phi: K \rightarrow K$ is well defined.
(ii) If $\left(H_{3}\right)$ holds and $r^{M}>1$, then $\Phi: K \rightarrow K$ is well defined.

Proof: For any $x \in K$, it is clear that $\Phi x \in$ $C^{1}(\mathbb{T}, \mathbb{R})$. In view of (7), for $t \in \mathbb{T}$, we obtain

$$
\begin{aligned}
&(\Phi x)(t+\omega)=\int_{t+\omega}^{t+2 \omega} G(t+\omega, s) x(s) \\
& \times\left[a(s) x(s)+\sum_{j=1}^{n} a_{j}(s) x\left(s-\tau_{j}(s)\right)\right. \\
&+\sum_{j=1}^{n} b_{j}(s) \int_{-T_{j}}^{0} K_{j}(\theta) x(\theta+s) \Delta \theta \\
&\left.+\sum_{j=1}^{n} c_{j}(s) x^{\Delta}\left(s-\sigma_{j}(s)\right)\right] \Delta s \\
&+\sum_{k: t_{k} \in[t+\omega, t+2 \omega)_{\mathbb{T}}} G\left(t+\omega, t_{k}\right) e_{r}\left(\sigma\left(t_{k}\right), t_{k}\right) \\
& \quad \times I_{k}\left(x\left(t_{k}\right)\right) \quad \int_{t}^{t+\omega} G(t+\omega, u+\omega) x(u+\omega) \\
& \quad \times[a(u+\omega) x(u+\omega) \\
& \quad+\sum_{j=1}^{n} a_{j}(u+\omega) x\left(u+\omega-\tau_{j}(u+\omega)\right) \\
& \quad+\sum_{j=1}^{n} b_{j}(u+\omega) \int_{-T_{j}}^{0} K_{j}(\theta) x(\theta+u+\omega) \Delta \theta
\end{aligned}
$$

$$
\begin{aligned}
& \left.+\sum_{j=1}^{n} c_{j}(u+\omega) x^{\Delta}\left(u+\omega-\sigma_{j}(u+\omega)\right)\right] \Delta u \\
& +\sum_{k: t_{k} \in[t, t+\omega)_{\mathbb{T}}} G\left(t+\omega, t_{k}+\omega\right) \\
& \times e_{r}\left(\sigma\left(t_{k}+\omega\right), t_{k}+\omega\right) I_{k}\left(x\left(t_{k}+\omega\right)\right) \\
= & \int_{t}^{t+\omega} G(t, u) x(u)[a(u) x(u) \\
& +\sum_{j=1}^{n} a_{j}(u) x\left(u-\tau_{j}(u)\right) \\
& +\sum_{j=1}^{n} b_{j}(u) \int_{-T_{j}}^{0} K_{j}(\theta) x(\theta+u) \Delta \theta \\
& \left.+\sum_{j=1}^{n} c_{j}(u) x^{\Delta}\left(u-\sigma_{j}(u)\right)\right] \Delta u \\
& +\sum_{k: t_{k} \in[t, t+\omega)_{\mathbb{T}}} G\left(t, t_{k}\right) e_{r}\left(\sigma\left(t_{k}\right), t_{k}\right) I_{k}\left(x\left(t_{k}\right)\right) \\
= & (\Phi x)(t) .
\end{aligned}
$$

That is, $(\Phi x)(t+\omega)=(\Phi x)(t), t \in \mathbb{R}$. So $\Phi x \in C_{\omega}^{1}$. In view of $\left(H_{1}\right)$, for $x \in K, t \in[0, \omega]_{\mathbb{T}}$, we have

$$
\begin{align*}
& a(t) x(t)+\sum_{j=1}^{n} a_{j}(t) x\left(t-\tau_{j}(t)\right) \\
& +\sum_{j=1}^{n} b_{j}(t) \int_{-T_{j}}^{0} K_{j}(\theta) x(\theta+t) \Delta \theta \\
& +\sum_{j=1}^{n} c_{j}(t) x^{\Delta}\left(t-\sigma_{j}(t)\right) \\
\geq & a(t) x(t)+\sum_{j=1}^{n} a_{j}(t) x\left(t-\tau_{j}(t)\right) \\
& +\sum_{j=1}^{n} b_{j}(t) \int_{-T_{j}}^{0} K_{j}(\theta) x(\theta+t) \Delta \theta \\
& -\sum_{j=1}^{n} c_{j}(t)\left|x^{\Delta}\left(t-\sigma_{j}(t)\right)\right| \\
\geq & \Theta a(t)\left|x^{\Delta}\right|_{1}+\sum_{j=1}^{n} \Theta a_{j}(t)\left|x^{\Delta}\right|_{1} \\
& +\sum_{j=1}^{n} \Theta b_{j}(t)\left|x^{\Delta}\right|_{1}-\sum_{j=1}^{n} c_{j}(t)\left|x^{\Delta}\right|_{1} \\
= & {\left[\Theta a(t)+\sum_{j=1}^{n} \Theta a_{j}(t)+\sum_{j=1}^{n} \Theta b_{j}(t)\right.} \\
& \left.-\sum_{j=1}^{n} c_{j}(t)\right]\left|x^{\Delta}\right|_{1} \geq 0 .  \tag{8}\\
&
\end{align*}
$$

Therefore, for $x \in K, t \in[0, \omega]_{\mathbb{T}}$, we can get

$$
\begin{aligned}
& |\Phi x|_{0} \leq B \int_{0}^{\omega} x(s)[a(s) x(s) \\
& +\sum_{j=1}^{n} a_{j}(s) x\left(s-\tau_{j}(s)\right) \\
& +\sum_{j=1}^{n} b_{j}(s) \int_{-T_{j}}^{0} K_{j}(\theta) x(\theta+s) \Delta \theta \\
& \left.+\sum_{j=1}^{n} c_{j}(s) x^{\Delta}\left(s-\sigma_{j}(s)\right)\right] \Delta s \\
& +B \sum_{k=1}^{n} I_{k}\left(x\left(t_{k}\right)\right)
\end{aligned}
$$

and

$$
\begin{align*}
(\Phi x)(t) \geq & A \int_{t}^{t+\omega} x(s)[a(s) x(s) \\
& +\sum_{j=1}^{n} a_{j}(s) x\left(s-\tau_{j}(s)\right) \\
& +\sum_{j=1}^{n} b_{j}(s) \int_{-T_{j}}^{0} K_{j}(\theta) x(\theta+s) \Delta \theta \\
& \left.+\sum_{j=1}^{n} c_{j}(s) x^{\Delta}\left(s-\sigma_{j}(s)\right)\right] \Delta s \\
& +A \sum_{k=1}^{p} I_{k}\left(x\left(t_{k}\right)\right) \\
\geq & \Theta|\Phi x|_{0} . \tag{9}
\end{align*}
$$

Now, we show that

$$
(\Phi x)^{\Delta}(t) \geq \Theta\left|(\Phi x)^{\Delta}\right|_{0}, \quad t \in[0, \omega]_{\mathbb{T}}
$$

In fact, from (7) we have

$$
\begin{align*}
(\Phi x)^{\Delta}(t)= & r(t)(\Phi x)(t)-x(t)[a(t) x(t) \\
& +\sum_{j=1}^{n} a_{j}(t) x\left(t-\tau_{j}(t)\right) \\
& +\sum_{j=1}^{n} b_{j}(t) \int_{-T_{j}}^{0} K_{j}(\theta) x(\theta+t) \Delta \theta \\
& \left.+\sum_{j=1}^{n} c_{j}(t) x^{\Delta}\left(t-\sigma_{j}(t)\right)\right] \tag{10}
\end{align*}
$$

It follows from (8) and (10) that if $(\Phi x)^{\Delta}(t) \geq 0$, then

$$
\begin{align*}
(\Phi x)^{\Delta}(t) & \leq r(t)(\Phi x)(t) \leq r^{M}(\Phi x)(t) \\
& \leq(\Phi x)(t) \tag{11}
\end{align*}
$$

On the other hand, from (9), (10) and $\left(H_{2}\right)$, if $(\Phi x)^{\Delta}(t)<0$, then

$$
\begin{aligned}
& -(\Phi x)^{\Delta}(t) \\
= & x(t)\left[a(t) x(t)+\sum_{j=1}^{n} a_{j}(t) x\left(t-\tau_{j}(t)\right)\right. \\
& +\sum_{j=1}^{n} b_{j}(t) \int_{-T_{j}}^{0} K_{j}(\theta) x(\theta+t) \Delta \theta \\
& \left.+\sum_{j=1}^{n} c_{j}(t) x^{\Delta}\left(t-\sigma_{j}(t)\right)\right]-r(t)(\Phi x)(t) \\
\leq & |x|_{1}^{2}\left[a(t)+\sum_{j=1}^{n} a_{j}(t)+\sum_{j=1}^{n} b_{j}(t)+\sum_{j=1}^{n} c_{j}(t)\right] \\
& -r^{m}(\Phi x)(t)
\end{aligned}
$$

$$
\leq\left(1+r^{m}\right) A_{0} \Theta|x|_{1}^{2} \int_{0}^{\omega}\left[\Theta a(s)+\sum_{j=1}^{n} \Theta a_{j}(s)\right.
$$

$$
\left.+\sum_{j=1}^{n} \Theta b_{j}(s)-\sum_{j=1}^{n} c_{j}(s)\right] \Delta s-r^{m}(\Phi x)(t)
$$

$$
=\left(1+r^{m}\right) \int_{0}^{\omega} A_{0} \Theta|x|_{1}\left[\Theta|x|_{1} a(s)\right.
$$

$$
+\sum_{j=1}^{n} \Theta|x|_{1} a_{j}(s)+\sum_{j=1}^{n} \Theta|x|_{1} b_{j}(s)
$$

$$
\left.-\sum_{j=1}^{n}|x|_{1} c_{j}(s)\right] \Delta s-r^{m}(\Phi x)(t)
$$

$$
\leq\left(1+r^{m}\right) \int_{t}^{t+\omega} G(t, s) x(s)[a(s) x(s)
$$

$$
+\sum_{j=1}^{n} a_{j}(s) x\left(s-\tau_{j}(s)\right)
$$

$$
+\sum_{j=1}^{n} b_{j}(s) \int_{-T_{j}}^{0} K_{j}(\theta) x(\theta+s) \Delta \theta
$$

$$
\left.-\sum_{j=1}^{n} c_{j}(s)\left|x^{\Delta}\left(s-\sigma_{j}(s)\right)\right|\right] \Delta s-r^{m}(\Phi x)(t)
$$

$$
\leq\left(1+r^{m}\right) \int_{t}^{t+\omega} G(t, s) x(s)[a(s) x(s)
$$

$$
+\sum_{j=1}^{n} a_{j}(s) x\left(s-\tau_{j}(s)\right)
$$

$$
+\sum_{j=1}^{n} b_{j}(s) \int_{-T_{j}}^{0} K_{j}(\theta) x(\theta+s) \Delta \theta
$$

$$
\left.+\sum_{j=1}^{n} c_{j}(s) x^{\Delta}\left(s-\sigma_{j}(s)\right)\right] \Delta s-r^{m}(\Phi x)(t)
$$

$$
\begin{align*}
& =\left(1+r^{m}\right)(\Phi x)(t)-r^{m}(\Phi x)(t) \\
& =(\Phi x)(t) \tag{12}
\end{align*}
$$

It follows from (11) and (12) that $\left|(\Phi x)^{\Delta}\right|_{0} \leq|\Phi x|_{0}$. So $|\Phi x|_{1}=|\Phi x|_{0}$. By (9) we have $(\Phi x)(t) \geq$ $\Theta|\Phi x|_{1}$. Hence, $\Phi x \in K$. The proof of $(i)$ is completed.
(ii) In view of the proof of $(i)$, we only need to prove that $(\Phi x)^{\Delta}(t) \geq 0$ implies

$$
(\Phi x)^{\Delta}(t) \leq(\Phi x)(t)
$$

From (8), (10), $\left(H_{1}\right)$ and $\left(H_{3}\right)$, we obtain

$$
\begin{aligned}
& \left(\Phi_{i} x\right)^{\Delta}(t) \\
& \leq r(t)(\Phi x)(t)-\Theta|x|_{1}[a(t) x(t) \\
& +\sum_{j=1}^{n} a_{j}(t) x\left(t-\tau_{j}(t)\right) \\
& +\sum_{j=1}^{n} b_{j}(t) \int_{-T_{j}}^{0} K_{j}(\theta) x(\theta+t) \Delta \theta \\
& \left.-\sum_{j=1}^{n} c_{j}(t)\left|x^{\Delta}\left(t-\sigma_{j}(t)\right)\right|\right] \\
& \leq r(t)(\Phi x)(t)-\Theta|x|_{1}^{2}\left[a(t)+\sum_{j=1}^{n} a_{j}(t)\right. \\
& \left.+\sum_{j=1}^{n} b_{j}(t)-\sum_{j=1}^{n} c_{j}(t)\right] \\
& \leq r^{M}(\Phi x)(t)-\Theta|x|_{1}^{2} \frac{r^{M}-1}{\Theta} B_{0} \\
& \times \int_{0}^{\omega}\left[a(s)+\sum_{j=1}^{n} a_{j}(s)+\sum_{j=1}^{n} b_{j}(s)\right. \\
& \left.+\sum_{j=1}^{n} c_{j}(s)\right] \Delta s \\
& \leq r^{M}(\Phi x)(t)-\left(r^{M}-1\right) \int_{t}^{t+\omega} B_{0}|x|_{1} \\
& \times\left[a(s)|x|_{1}+\sum_{j=1}^{n} a_{j}(s)|x|_{1}\right. \\
& \left.+\sum_{j=1}^{n} b_{j}(s)|x|_{1}+\sum_{j=1}^{n} c_{j}(s)|x|_{1}\right] \Delta s \\
& \leq r^{M}(\Phi x)(t)-\left(r^{M}-1\right) \int_{t}^{t+\omega} G(t, s) x(s) \\
& \times\left[a(s) x(s)+\sum_{j=1}^{n} a_{j}(s) x\left(s-\tau_{j}(s)\right)\right.
\end{aligned}
$$

$$
\begin{aligned}
& +\sum_{j=1}^{n} b_{j}(s) \int_{-T_{k}}^{0} K_{j}(\theta) x(\theta+s) \Delta \theta \\
& \left.+\sum_{j=1}^{n} c_{j}(s)\left|x^{\Delta}\left(s-\sigma_{j}(s)\right)\right|\right] \Delta s \\
\leq & r^{M}(\Phi x)(t)-\left(r^{M}-1\right) \int_{t}^{t+\omega} G(t, s) x(s) \\
& \times\left[a(s) x(s)+\sum_{j=1}^{n} a_{j}(s) x\left(s-\tau_{j}(s)\right)\right. \\
& +\sum_{j=1}^{n} b_{j}(s) \int_{-T_{k}}^{0} K_{j}(\theta) x(\theta+s) \Delta \theta \\
& \left.+\sum_{j=1}^{n} c_{j}(s) x^{\Delta}\left(s-\sigma_{j}(s)\right)\right] \Delta s \\
= & r^{M}(\Phi x)(t)-\left(r^{M}-1\right)(\Phi x)(t) \\
= & (\Phi x)(t)
\end{aligned}
$$

The proof of $(i i)$ is completed.
Lemma 8. Assume that $\left(H_{1}\right)-\left(H_{2}\right),\left(H_{4}\right)$ hold and $R \sum_{j=1}^{n} c_{j}^{M}<1$.
(i) If $r^{M} \leq 1$, then $\Phi: K \bigcap \bar{\Omega}_{R} \rightarrow K$ is strict-setcontractive;
(ii) If $\left(H_{3}\right)$ holds and $r^{M}>1$, then $\Phi: K \bigcap \bar{\Omega}_{R} \rightarrow$ $K$ is strict-set-contractive;
where $\Omega_{R}=\left\{x \in C_{\omega}^{1}:|x|_{1}<R\right\}$.
Proof: We only need to prove $(i)$, since the proof of $(i i)$ is similar. It is easy to see that $\Phi$ is continuous and bounded. Now we prove that $\alpha_{C_{\omega}^{1}}(\Phi(S)) \leq$ $\left(R \sum_{j=1}^{n} c_{j}^{M}\right) \alpha_{C_{\omega}^{1}}(S)$ for any bounded set $S \subset \bar{\Omega}_{R}$. Let $\eta=\alpha_{C_{\omega}^{1}}(S)$. Then, for any positive number $\varepsilon<\left(R \sum_{j=1}^{n} c_{j}^{M}\right) \eta$, there is a finite family of subsets $\left\{S_{i}\right\}$ satisfying $S=\bigcup_{i} S_{i}$ with $\operatorname{diam}\left(S_{i}\right) \leq \eta+\varepsilon$. Therefore

$$
\begin{equation*}
|x-y|_{1} \leq \eta+\varepsilon \quad \text { for any } x, y \in S_{i} \tag{13}
\end{equation*}
$$

As $S$ and $S_{i}$ are precompact in $C_{\omega}^{0}$, it follows that there is a finite family of subsets $\left\{S_{i j}\right\}$ of $S_{i}$ such that $S_{i}=\bigcup_{j} S_{i j}$ and

$$
\begin{equation*}
|x-y|_{0} \leq \varepsilon \quad \text { for any } x, y \in S_{i j} \tag{14}
\end{equation*}
$$

In addition, for any $x \in S$ and $t \in[0, \omega]_{\mathbb{T}}$, we have

$$
|(\Phi x)(t)|=\int_{t}^{t+\omega} G(t, s) x(s)[a(s) x(s)
$$

$$
\begin{aligned}
& \quad+\sum_{j=1}^{n} a_{j}(s) x\left(s-\tau_{j}(s)\right) \\
& \quad+\sum_{j=1}^{n} b_{j}(s) \int_{-T_{j}}^{0} K_{j}(\theta) x(\theta+s) \Delta \theta \\
& \left.\quad+\sum_{j=1}^{n} c_{j}(s) x^{\Delta}\left(s-\sigma_{j}(s)\right)\right] \Delta s \\
& \quad+\sum_{k: t_{k} \in[t, t+\omega)_{\mathbb{T}}} G\left(t, t_{k}\right) e_{r}\left(\sigma\left(t_{k}\right), t_{k}\right) I_{k}\left(x\left(t_{k}\right)\right) \\
& \leq \quad B R^{2} \int_{t}^{t+\omega}\left[a(s)+\sum_{j=1}^{n} a_{j}(s)+\sum_{j=1}^{n} b_{j}(s)\right. \\
& \left.\quad+\sum_{j=1}^{n} c_{j}(s)\right] \Delta s+B M|x|_{0}:=H
\end{aligned}
$$

and

$$
\begin{aligned}
\left|(\Phi x)^{\Delta}(t)\right|= & \mid r(t)(\Phi x)(t)-x(t)[a(t) x(t) \\
& +\sum_{j=1}^{n} a_{j}(t) x\left(t-\tau_{j}(t)\right) \\
& +\sum_{j=1}^{n} b_{j}(t) \int_{-T_{j}}^{0} K_{j}(\theta) x(\theta+t) \Delta \theta \\
& \left.+\sum_{j=1}^{n} c_{j}(t) x^{\Delta}\left(t-\sigma_{j}(t)\right)\right] \mid \\
\leq & r^{M} H+R^{2} \sum_{j=1}^{n}\left(a^{M}+a_{j}^{M}+b_{j}^{M}+c_{j}^{M}\right)
\end{aligned}
$$

Applying the Arzela-Ascoli Theorem, we know that $\Phi(S)$ is precompact in $C_{\omega}^{0}$. Then, there is a finite family of subsets $\left\{S_{i j k}\right\}$ of $S_{i j}$ such that $S_{i j}=\bigcup_{k} S_{i j k}$ and

$$
\begin{equation*}
|\Phi x-\Phi y|_{0} \leq \varepsilon, \forall x, y \in S_{i j k} \tag{15}
\end{equation*}
$$

From (8), (10), (13)-(15) and ( $H_{1}$ ), for any $x, y \in$ $S_{i j k}$, we obtain

$$
\begin{aligned}
& \left|(\Phi x)^{\Delta}-(\Phi y)^{\Delta}\right|_{0} \\
= & \max _{t \in[0, \omega]_{\mathbb{T}}}\{\mid r(t)(\Phi x)(t)-r(t)(\Phi y)(t) \\
& -x(t)\left[a(t) x(t)+\sum_{j=1}^{n} a_{j}(t) x\left(t-\tau_{j}(t)\right)\right. \\
& +\sum_{j=1}^{n} b_{j}(t) \int_{-T_{j}}^{0} K_{j}(\theta) x(\theta+t) \Delta \theta \\
& \left.+\sum_{j=1}^{n} c_{j}(t) x^{\Delta}\left(t-\sigma_{j}(t)\right)\right]
\end{aligned}
$$

$$
\begin{aligned}
& +y(t)\left[a(t) y(t)+\sum_{j=1}^{n} a_{j}(t) y\left(t-\tau_{j}(t)\right)\right. \\
& +\sum_{j=1}^{n} b_{j}(t) \int_{-T_{j}}^{0} K_{j}(\theta) y(\theta+t) \Delta \theta \\
& \left.\left.+\sum_{j=1}^{n} c_{j}(t) y^{\Delta}\left(t-\sigma_{j}(t)\right)\right] \mid\right\} \\
& \leq \max _{t \in[0, \omega]_{\mathbb{T}}}\{|r(t)[(\Phi x)(t)-(\Phi y)(t)]|\} \\
& +\max _{t \in[0, \omega]_{\mathbb{T}}}\{\mid x(t)[a(t) x(t) \\
& +\sum_{j=1}^{n} a_{j}(t) x\left(t-\tau_{j}(t)\right) \\
& +\sum_{j=1}^{n} b_{j}(t) \int_{-T_{j}}^{0} K_{j}(\theta) x(\theta+t) \Delta \theta \\
& \left.+\sum_{j=1}^{n} c_{j}(t) x^{\Delta}\left(t-\sigma_{j}(t)\right)\right] \\
& -y(t)\left[a(t) y(t)+\sum_{j=1}^{n} a_{j}(t) y\left(t-\tau_{j}(t)\right)\right. \\
& +\sum_{j=1}^{n} b_{j}(t) \int_{-T_{j}}^{0} K_{j}(\theta) y(\theta+t) \Delta \theta \\
& \left.\left.+\sum_{j=1}^{n} c_{j}(t) y^{\Delta}\left(t-\sigma_{j}(t)\right)\right] \mid\right\} \\
& \leq r^{M}|(\Phi x)-(\Phi y)|_{0} \\
& +\max _{t \in[0, \omega]_{\mathbb{T}}}\{\mid x(t)[(a(t) x(t) \\
& +\sum_{j=1}^{n} a_{j}(t) x\left(t-\tau_{j}(t)\right) \\
& +\sum_{j=1}^{n} b_{j}(t) \int_{-T_{j}}^{0} K_{j}(\theta) x(\theta+t) \Delta \theta \\
& \left.+\sum_{j=1}^{n} c_{j}(t) x^{\Delta}\left(t-\sigma_{j}(t)\right)\right) \\
& -\left(a(t) y(t)+\sum_{j=1}^{n} a_{j}(t) y\left(t-\tau_{j}(t)\right)\right. \\
& +\sum_{j=1}^{n} b_{j}(t) \int_{-T_{j}}^{0} K_{j}(\theta) y(\theta+t) \Delta \theta \\
& \left.\left.\left.+\sum_{j=1}^{n} c_{j}(t) y^{\Delta}\left(t-\sigma_{j}(t)\right)\right)\right] \mid\right\} \\
& +\max _{t \in[0, \omega]_{\mathbb{T}}}\{\mid y(t)[a(t) y(t)
\end{aligned}
$$

$$
\begin{align*}
& +\sum_{j=1}^{n} a_{j}(t) y\left(t-\tau_{j}(t)\right) \\
& +\sum_{j=1}^{n} b_{j}(t) \int_{-T_{j}}^{0} K_{j}(\theta) y(\theta+t) \Delta \theta \\
& \left.\left.+\sum_{j=1}^{n} c_{j}(t) y^{\Delta}\left(t-\sigma_{j}(t)\right)\right][x(t)-y(t)] \mid\right\} \\
& \leq r^{M} \varepsilon+R \max _{t \in[0, \omega]_{\mathbb{T}}}\{a(t)|x(t)-y(t)| \\
& +\sum_{j=1}^{n} a_{j}(t)\left|x\left(t-\tau_{j}(t)\right)-y\left(t-\tau_{j}(t)\right)\right| \\
& +\sum_{j=1}^{n} b_{j}(t) \int_{-T_{j}}^{0} K_{j}(\theta) \mid x(\theta+t) \\
& -y(\theta+t) \mid \Delta \theta \\
& \left.+\sum_{j=1}^{n} c_{j}(t)\left|x^{\Delta}\left(t-\sigma_{j}(t)\right)-y^{\Delta}\left(t-\sigma_{j}(t)\right)\right|\right\} \\
& +\varepsilon \max _{t \in[0, \omega]_{\mathbb{T}}}\left\{a(t) y(t)+\sum_{j=1}^{n} a_{j}(t) y\left(t-\tau_{j}(t)\right)\right. \\
& +\sum_{j=1}^{n} b_{j}(t) \int_{-T_{j}}^{0} K_{j}(\theta) y(\theta+t) \Delta \theta \\
& \left.+\sum_{j=1}^{n} c_{j}(t)\left|y^{\Delta}\left(t-\sigma_{j}(t)\right)\right|\right\} \\
& \leq r^{M} \varepsilon+\operatorname{R\varepsilon }\left(a^{M}+\sum_{j=1}^{n} a_{j}^{M}+\sum_{j=1}^{n} b_{j}^{M}\right) \\
& +R(\eta+\varepsilon)\left(\sum_{j=1}^{n} c_{j}^{M}\right) \\
& +R \varepsilon\left(a^{M}+\sum_{j=1}^{n} a_{j}^{M}+\sum_{j=1}^{n} b_{j}^{M}+\sum_{j=1}^{n} c_{j}^{M}\right) \\
& =\left(R \eta \sum_{j=1}^{n} c_{j}^{M}\right)+\hat{H} \varepsilon, \tag{16}
\end{align*}
$$

where $\widehat{H}=r^{M}+2 R\left[a^{M}+\sum_{j=1}^{n} a_{j}^{M}+\sum_{j=1}^{n} b_{j}^{M}+\sum_{j=1}^{n} c_{j}^{M}\right]$.
From (15) and (16) we have

$$
|\Phi x-\Phi y|_{1} \leq\left(R \sum_{j=1}^{n} c_{j}^{M}\right) \eta+\hat{H} \varepsilon, \forall x, y \in S_{i j k} .
$$

As $\varepsilon$ is arbitrary small, it follows that

$$
\alpha_{C_{\omega}^{1}}(\Phi(S)) \leq\left(R \sum_{j=1}^{n} c_{j}^{M}\right) \alpha_{C_{\omega}^{1}}(S) .
$$

Therefore, $\Phi$ is strict-set-contractive. This completes the proof.

## 3 Main Result

Our main result of this paper is as follows:
Theorem 9. Assume that $\left(H_{1}\right)-\left(H_{2}\right),\left(H_{4}\right)$ hold.
(i) If $r^{M} \leq 1$, then system (2) has at least one positive $\omega$-periodic solutions.
(ii) If $\left(H_{3}\right)$ holds and $r^{M}>1$, then system (2) has at least one positive $\omega$-periodic solutions.

Proof: We only need to prove $(i)$, since the proof of (ii) is similar. Let $R=\frac{1}{A \Theta \Gamma}$ and $0<r<\frac{\Theta-B M}{B \Pi}$. Then we have $0<r<R$. From Lemma 7 and Lemma 8, we know that $\Phi$ is strict-set-contractive on $K_{r, R}$. In view of (10), we see that if there exists $x^{*} \in K$ such that $\Phi x^{*}=x^{*}$, then $x^{*}$ is one positive $\omega$-periodic solution of system (2). Now, we shall prove that condition (ii) of Lemma 6 hold.

First, we prove that $\Phi x \nsupseteq x, \forall x \in K,|x|_{1}=r$. Otherwise, there exists $x \in K,|x|_{1}=r$ such that $\Phi x \geq x$. So $|x|>0$ and $\Phi x-x \in K$, which implies that

$$
\begin{equation*}
(\Phi x)(t)-x(t) \geq \Theta|\Phi x-x|_{1} \geq 0, \forall t \in[0, \omega]_{\mathbb{T}} . \tag{17}
\end{equation*}
$$

Moreover, for $t \in[0, \omega]_{\mathbb{T}}$, by $\left(H_{4}\right)$, we have

$$
\begin{align*}
& (\Phi x)(t) \\
= & \int_{t}^{t+\omega} G(t, s) x(s)[a(s) x(s) \\
& +\sum_{j=1}^{n} a_{j}(s) x\left(s-\tau_{j}(s)\right) \\
& +\sum_{j=1}^{n} b_{j}(s) \int_{-T_{j}}^{0} K_{j}(\theta) x(\theta+s) \Delta \theta \\
& \left.+\sum_{j=1}^{n} c_{j}(s) x^{\Delta}\left(s-\sigma_{j}(s)\right)\right] \Delta s \\
& +\sum_{k: t_{k} \in[t, t+\omega)_{\mathbb{T}}} G\left(t, t_{k}\right) e_{r}\left(\sigma\left(t_{k}\right), t_{k}\right) I_{k}\left(x\left(t_{k}\right)\right) \\
\leq & B r|x|_{0} \int_{0}^{\omega}\left[a(s)+\sum_{j=1}^{n} a_{j}(s)\right. \\
& \left.+\sum_{j=1}^{n} b_{j}(s)+\sum_{j=1}^{n} c_{j}(s)\right] \Delta s+B M|x|_{0} \\
= & B(r \Pi+M)|x|_{0} \\
< & \Theta|x|_{0} . \tag{18}
\end{align*}
$$

In view of (17) and (18), we have

$$
|x|_{0} \leq|\Phi x|<\Theta|x|_{0}<|x|_{0}
$$

which is a contradiction.
Finally, we prove that $\Phi x \not \leq x, \forall x \in K,|x|_{1}=$ $R$ also holds. For this case, we only need to prove that

$$
\Phi x \nless x, x \in K,|x|_{1}=R .
$$

Suppose, for the sake of contradiction, that there exists $x \in K$ and $|x|_{1}=R$ such that $\Phi x<x$, thus $x-\Phi x \in K \backslash\{0\}$. Furthermore, for any $t \in[0, \omega]_{\mathbb{T}}$, we have

$$
\begin{equation*}
x(t)-(\Phi x)(t) \geq \Theta|x-\Phi x|_{1}>0 \tag{19}
\end{equation*}
$$

In addition, for any $t \in[0, \omega]_{\mathbb{T}}$, we find

$$
\begin{align*}
& (\Phi x)(t) \\
= & \int_{t}^{t+\omega} G(t, s) x(s)[a(s) x(s) \\
& +\sum_{j=1}^{n} a_{j}(s) x\left(s-\tau_{j}(s)\right) \\
& +\sum_{j=1}^{n} b_{j}(s) \int_{-T_{j}}^{0} K_{j}(\theta) x(\theta+s) \Delta \theta \\
& \left.+\sum_{j=1}^{n} c_{j}(s) x^{\Delta}\left(s-\sigma_{j}(s)\right)\right] \Delta s \\
& +\sum_{k: t_{k} \in[t, t+\omega)_{\mathbb{T}}} G\left(t, t_{k}\right) e_{r}\left(\sigma\left(t_{k}\right), t_{k}\right) I_{k}\left(x\left(t_{k}\right)\right) \\
\geq & A \Theta|x|_{1}^{2} \int_{0}^{\omega}\left[\Theta a(s)+\sum_{j=1}^{n} \Theta a_{j}(s)\right. \\
= & A \Theta \Gamma R^{2} \\
= & R .
\end{align*}
$$

From (19) and (20), we obtain

$$
|x|>|\Phi x|_{0} \geq R,
$$

which is a contradiction. Therefore, conditions $(i)$ and (ii) hold. By Lemma 6, we see that $\Phi$ has at least one nonzero fixed point in $K$. Therefore, system (2) has at least one positive $\omega$-periodic solutions. This completes the proof.

Remark 10. From the proof of our results, one can see that if all of or some of $T_{j}(j=1,2, \ldots, n)$ replaced by $\infty$, the conclusion of Theorem 9 remains true.

## 4 An example

Consider the following dynamic system on time scale $\mathbb{T}$,

$$
\left\{\begin{align*}
x^{\Delta}(t)= & x(t)\left[\frac{2+\cos t}{8 \pi}-(5-2 \sin t) x(t)\right.  \tag{21}\\
& -(2+\sin t) x(t-\tau(t)) \\
& -\left(1-\frac{2}{3} \sin t\right) \\
& \times \int_{-T_{1}}^{0} K_{1}(s) x(t+s) \Delta s \\
& \left.-\frac{1-\sin t}{20} x^{\Delta}(t-\sigma(t))\right], t \neq t_{k} \\
x\left(t_{k}^{+}\right)= & x\left(t_{k}^{-}\right)+0.01 \sin \left(x\left(t_{k}\right)\right), k=1,2, \cdots
\end{align*}\right.
$$

where $\tau, \sigma \in C(\mathbb{T}, \mathbb{T})$ are $2 \pi$-periodic functions with respect to their first arguments, respectively. $\quad T_{1} \in(0, \infty)_{\mathbb{T}}, K_{1} \in C\left(\left[-T_{1}, 0\right]_{\mathbb{T}},(0, \infty)\right)$, $\int_{-T_{1}}^{0} K_{1}(s) \Delta s=1$. Obviously,

$$
\begin{aligned}
& r(t)=\frac{2+\cos t}{8 \pi}, a(t)=5-2 \sin t \\
& a_{1}(t)=2+\sin t, b_{1}(t)=1-\frac{2}{3} \sin t \\
& c_{1}(t)=\frac{1-\sin t}{20}
\end{aligned}
$$

Let $\mathbb{T}=\mathbb{R}, p=2$, by a direct calculation, we can get $\Theta=e^{-\frac{1}{2}}, \Gamma=30.1734, \Pi=30.6781$, and

$$
\begin{aligned}
\left(H_{1}\right) & \Theta a(t)+\sum_{j=1}^{n} \Theta a_{j}(t)+\sum_{j=1}^{n} \Theta b_{j}(t)-\sum_{j=1}^{n} c_{j}(t) \\
& =e^{-\frac{1}{2}}\left(8.05+\frac{5}{3} \sin t\right)-\frac{1-\sin t}{20} \geq 3.7717>0 . \\
\left(H_{2}\right) & \left(1+r^{m}\right) A_{0} \Theta \Gamma=29.3335 \geq 9.7667= \\
& \max _{t \in[0,2 \pi]_{\mathbb{T}}}\left\{a(t)+\sum_{j=1}^{n} a_{i j}(t)+\sum_{j=1}^{n} b_{i j}(t)+\right. \\
& \left.\sum_{j=1}^{n} c_{i j}(t)\right\} .
\end{aligned}
$$

Hence, $\left(H_{1}\right),\left(H_{2}\right)$ hold. For $|x|_{0}>0$, then there exists a sufficient large number $M>0$ such that $\left(H_{4}\right)$ holds. Moreover, $r^{M}=\frac{3}{8 \pi} \leq 1$. According to Theorem 9, system (21) has at least one positive $2 \pi$-periodic solution.

Acknowledgements: This work is supported by the National Natural Sciences Foundation of People's Republic of China under Grant 61073065.

## References:

[1] Y. Kuang, Delay differential equations with applications in population dynamics, New York: Academic Press; 1993.
[2] Z. Yang, J. Cao, Existence of periodic solutions in neutral state-dependent delays equations and models, J. Comput. Appl. Math. 174, (2005), pp.179-199.
[3] S. Lu, On the existence of positive periodic solutions for neutral functional differential equation with multiple deviating arguments, J. Math. Anal. Appl., 280, (2003), pp.321-333.
[4] Y. Kuang, A. Feldstein, Boundedness of solutions of a nonlinear nonautonomous neutral delay equation, J. Math. Anal. Appl., 156, (1991), pp. 293-304.
[5] K. Gopalsamy, X. He, L. Wen, On a periodic neutral logistic equation, Glasgow Math. J., 33, (1991), pp.281-286.
[6] M. Bohner, A. Peterson, Dynamic equations on timescales, An Introduction with Applications, Boston: Birkhaüser; 2001.
[7] S. Hilger, Analysis on measure chains-a unified approach to continuous and discrete calculus, Results Math., 18, (1990), pp. 18-56.
[8] V. Spedding, Taming nature's numbers, New Scientist: The Global Science and Technology Weekly, 2404, (2003), pp.28-31.
[9] R. McKellar, K. Knight, A combined discretecontinuous model describing the lag phase of listeria monocytogenes, Int. J. Food Microbiol., 54, (2000), No.3, pp.171-180.
[10] C. Tisdell, A. Zaidi, Basic qualitative and qualitative results for solutions to nonlinear dynamic equations on time scales with an application to economic modelling, Nonlinear Anal. Theor., 68, (2008), No.11, pp.3504-3524.
[11] M. Fazly, M. Hesaaraki, Periodic solutions for predator-prey systems with BeddingtonDeAngelis functional response on time scales, Nonlinear Anal. Real., 9 (2008), No.3, pp. 12241235.
[12] Y. Li, M. Hu, Three positive periodic solutions for a class of higher-dimensional functional differential equations with impulses on time scales, Adv. Diff. Equ., 2009, Article ID 698463.
[13] L. Bi, M. Bohner, M. Fan, Periodic solutions of functional dynamic equations with infinite delay, Nonlinear Anal. Theor., 68, (2008), No.5, pp.1226-1245.
[14] Y. Li, L. Zhao, P. Liu, Existence and exponential stability of periodic solution of high-order Hopfield neural network with delays on time scales, Discrete Dyn. Nat. Soc., 2009, Article ID 573534.
[15] E.R. Kaufmann, Y.N. Raffoul, Periodic soluteons for a neutral nonlinear dynamical equation on a time scale, J. Math. Anal. Appl., 319, (2006), pp.315-325.
[16] N.P. Cac, J.A. Gatica, Fixed point theorems for mappings in ordered Banach spaces, J. Math. Anal. Appl., 71, (1979), pp.547-557.

